
Inferring Expected Runtimes for Probabilistic Integer Programs Using Expected Sizes

27th Conference on Tools and Algorithms for the Construction and Analysis of Systems

Fabian Meyer **Marcel Hark** Jürgen Giesl

Introduction

Randomization in Programming

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    x ← x - 1  
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 - Measure of efficiency: expected runtime.

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- Extension of classical programs by probability distributions.
 - efficiency of algorithms, cryptography, ...
- Termination behavior diversifies.
 - Measure of efficiency: expected runtime.
 - How to infer upper bounds on expected runtime **fully automatically**?

```
while (x > 0) {  
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Linear Probabilistic Ranking Functions (LPRF)

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Consider $\tau = 2 \cdot x$.

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Consider $\mathfrak{r} = 2 \cdot x$.

Whenever loop can be entered: $\mathfrak{r} > 0$.

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    {  $x \leftarrow x$  }  $\left[\frac{1}{2}\right]$  {  $x \leftarrow x - 1$  }  
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In one loop iteration \mathfrak{r} is expected to decrease by 1 in each iteration.

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$$\frac{1}{2} \cdot \mathfrak{r}[x/x] + \frac{1}{2} \cdot \mathfrak{r}[x/x-1] = 2 \cdot x - 1 = \mathfrak{r} - 1$$

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Expected runtime of loop: at most $\mathfrak{r} = 2 \cdot x$. (e.g., [Bournez & Garnier '05]).

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- What about larger programs?

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- Value of y grows in first loop.

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 - very successful for classical programs [Giesl et al. '16].

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- Computation of runtimes via sizes:
 - very successful for classical programs [Giesl et al. '16].
- **Contribution**: Novel **modular** approach by combining expected runtimes and expected sizes.

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Probabilistic Integer Transition Systems

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- We denote programs by graphs to capture control flow.

Probabilistic Integer Transition Systems

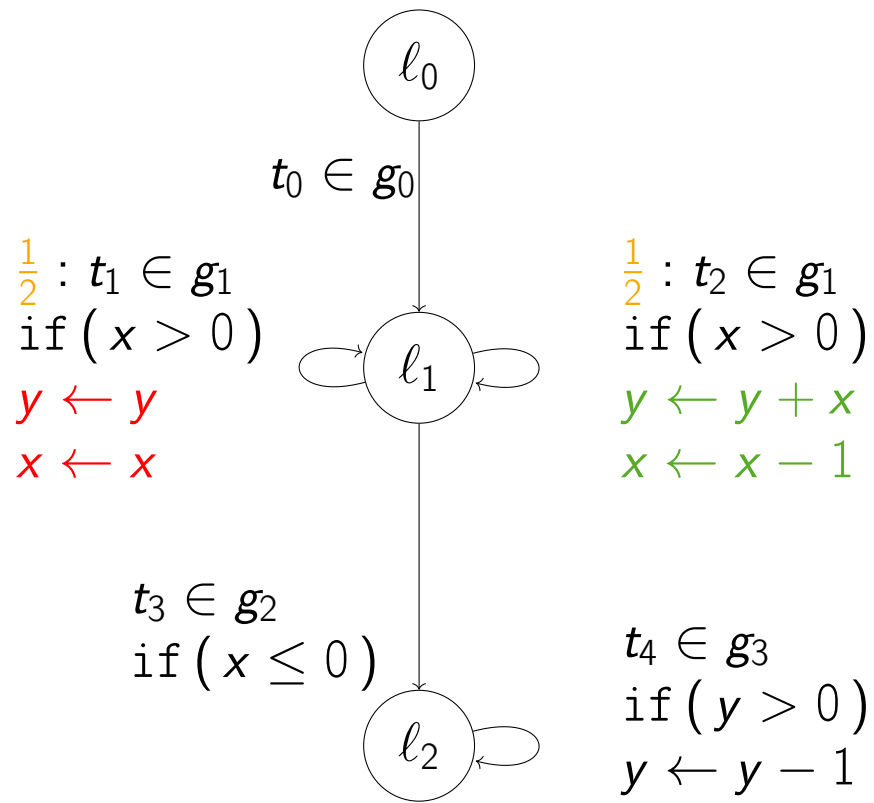
- We denote programs by graphs to capture control flow.

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    { y ← y } [1/2] { y ← y + x }  
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}  
while(y > 0) {  
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```

Introduction

Probabilistic Integer Transition Systems

- We denote programs by graphs to capture control flow.



```
l1: while(x > 0) {  
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    { x ← x }      { x ← x - 1 }  
}  
l2: while(y > 0) {  
    y ← y - 1  
}
```

Introduction

Outline

Introduction

Computing Expected Runtime Bounds

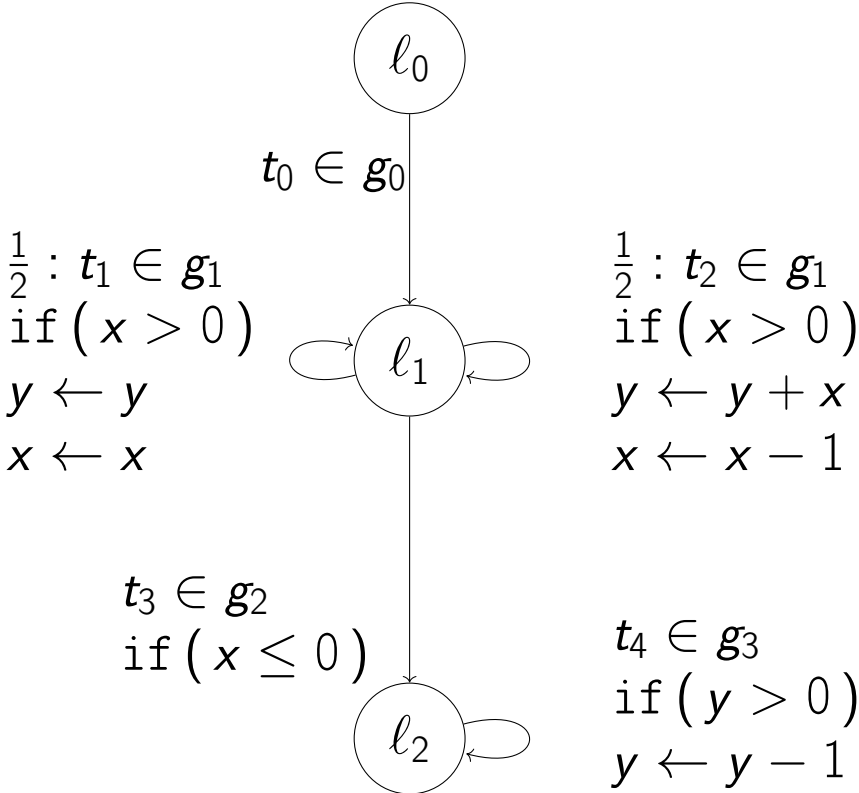
Computing Expected Size Bounds

Experiments

Conclusion

Computing Expected Runtime Bounds

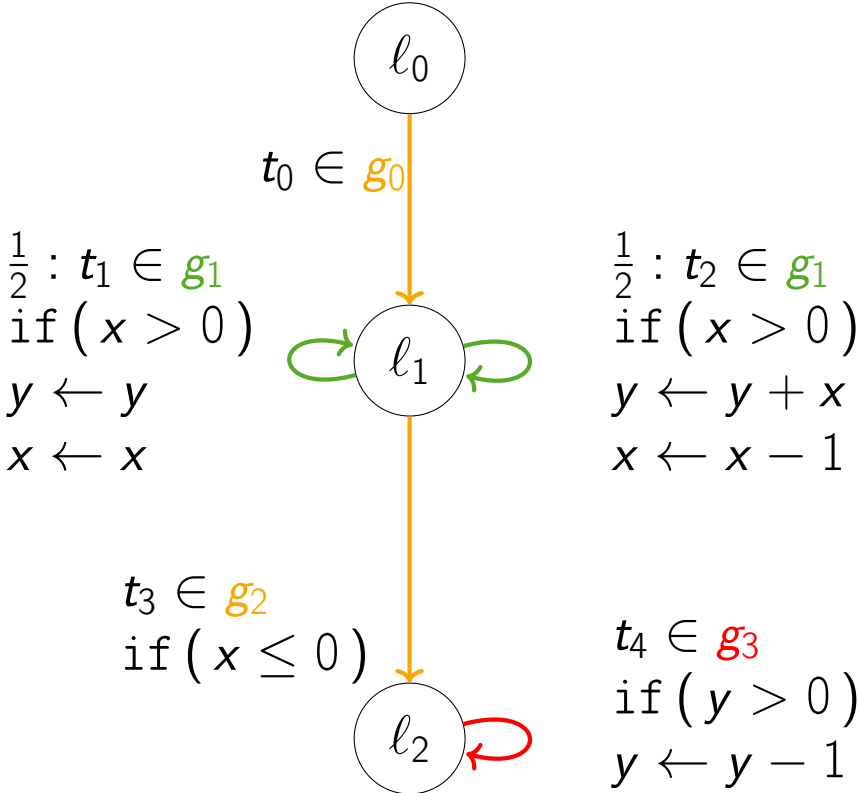
Overall Idea



Computing Expected Runtime Bounds

Overall Idea

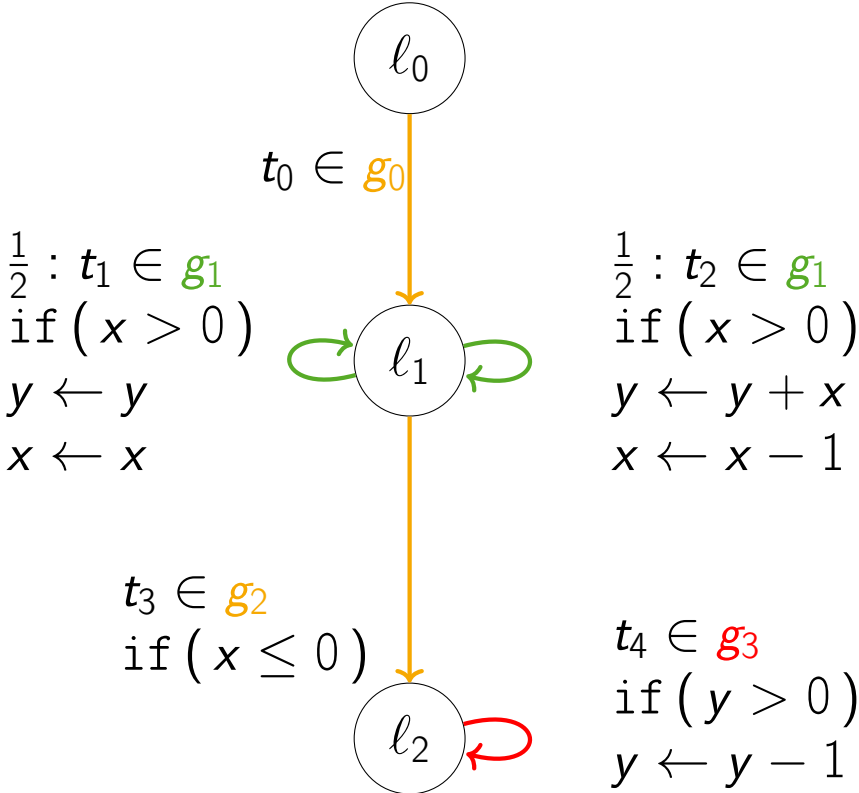
- For each general transition $g \in \mathcal{GT}$:



Computing Expected Runtime Bounds

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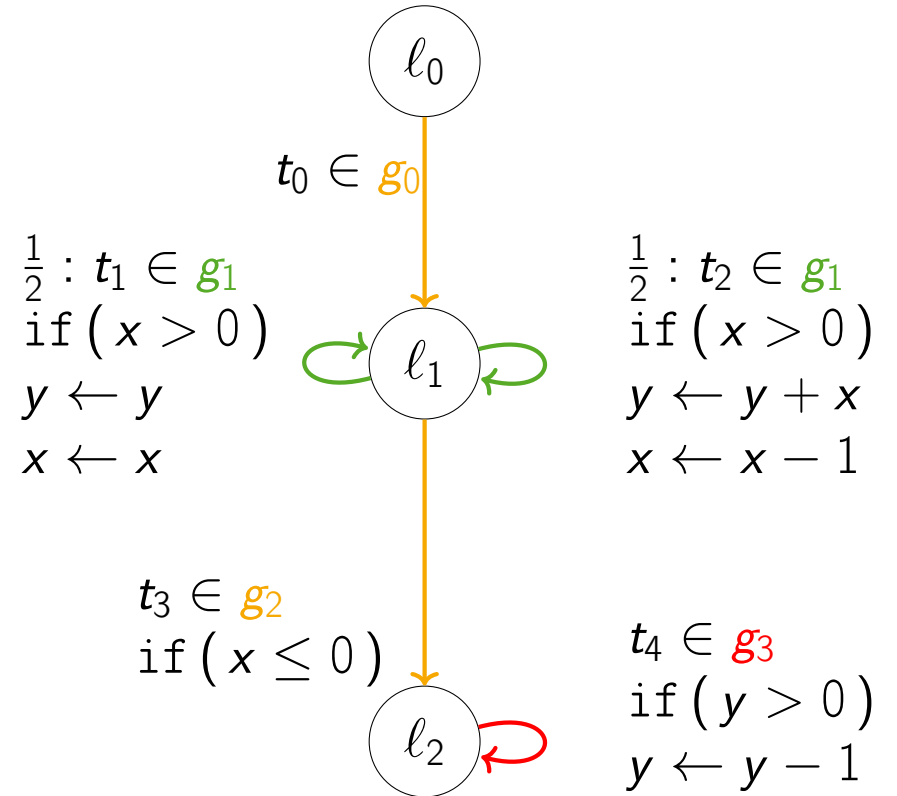
- For each general transition $g \in \mathcal{GT}$:
 $\mathcal{R}(g) =$ number of executions of g in run of full program.



Computing Expected Runtime Bounds

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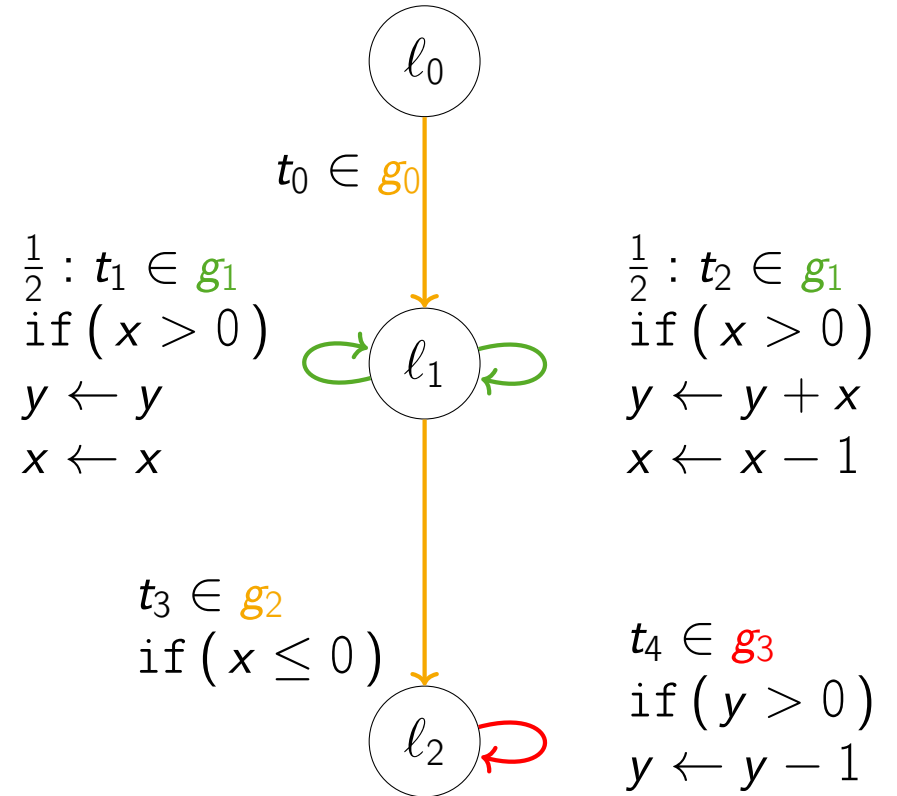
- For each general transition $g \in \mathcal{GT}$:
 $\mathcal{R}(g)$ = number of executions of g in run of full program.
- $\sum_{g \in \mathcal{GT}} \mathbb{E}(\mathcal{R}(g))$ is expected runtime of full program.



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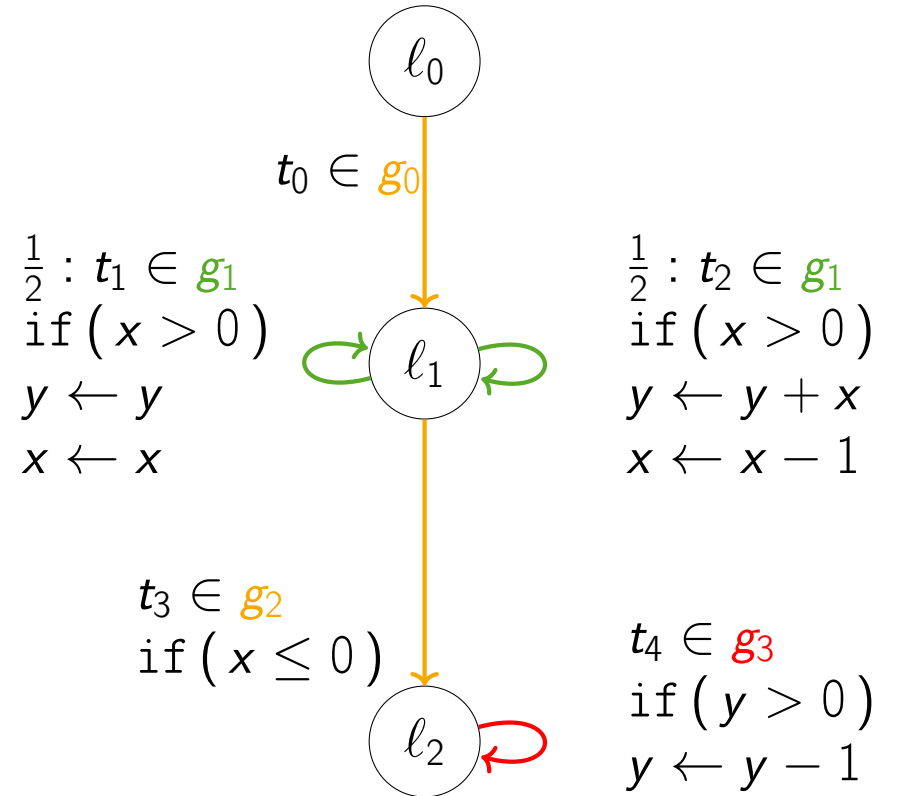
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 $\mathcal{R}(g)$ = number of executions of g in run of full program.
- $\sum_{g \in \mathcal{GT}} \mathbb{E}(\mathcal{R}(g))$ is expected runtime of full program.
→ Over-approximate $\mathbb{E}(\mathcal{R}(g))$ for each $g \in \mathcal{GT}$.



Computing Expected Runtime Bounds

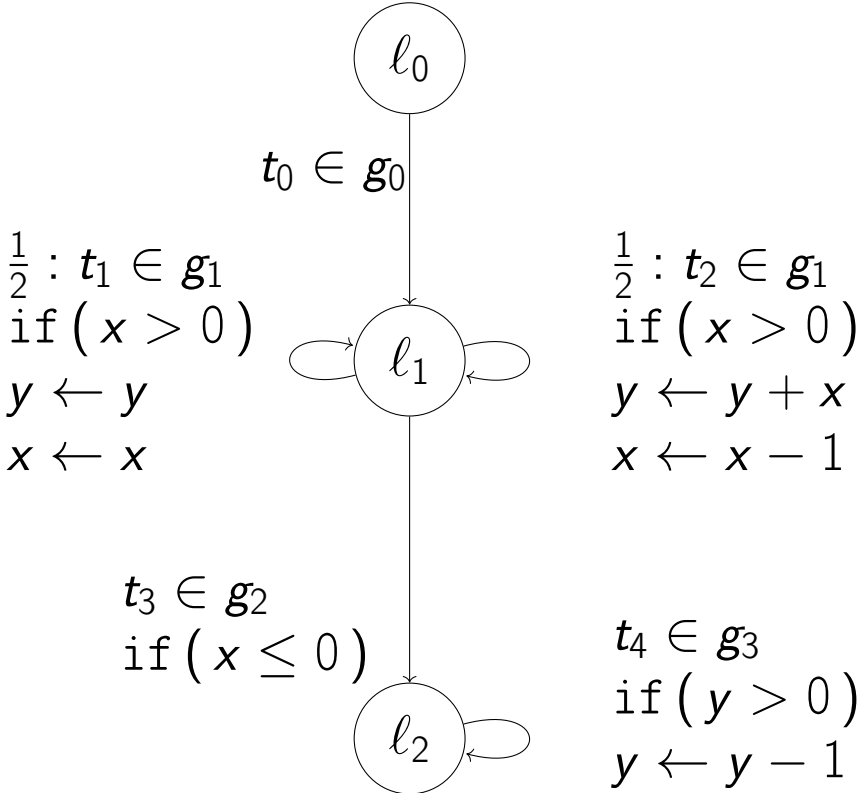
Overall Idea

- For each general transition $g \in \mathcal{GT}$:
 $\mathcal{R}(g)$ = number of executions of g in run of full program.
- $\sum_{g \in \mathcal{GT}} \mathbb{E}(\mathcal{R}(g))$ is expected runtime of full program.
 - Over-approximate $\mathbb{E}(\mathcal{R}(g))$ for each $g \in \mathcal{GT}$.
 - Contribution: **Modular** inference of bound on $\mathbb{E}(\mathcal{R}(g))$.



Computing Expected Runtime Bounds

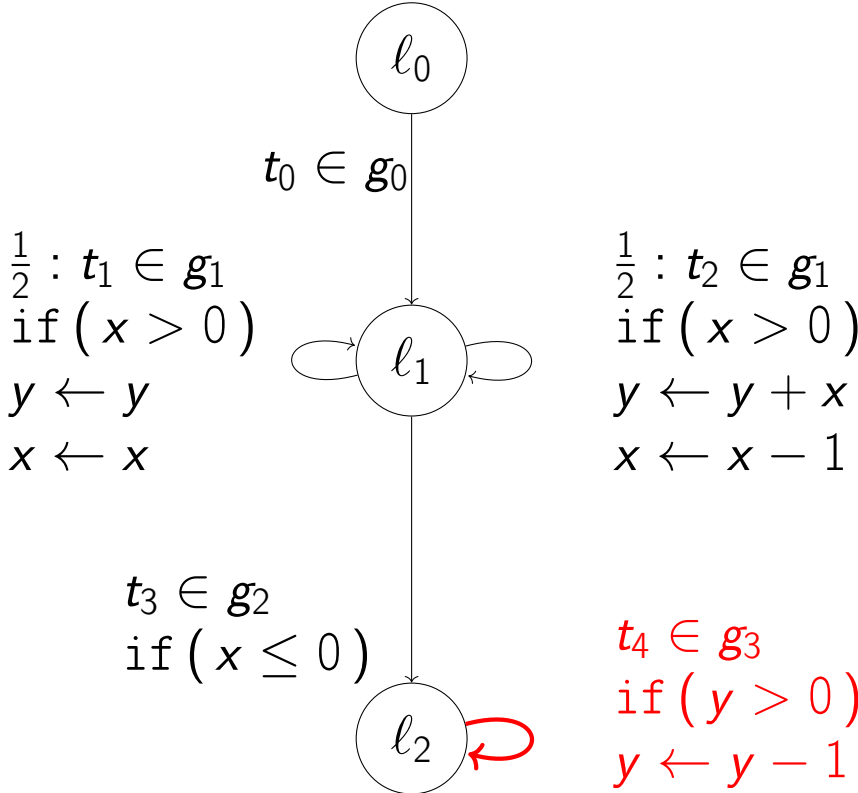
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Computing Expected Runtime Bounds

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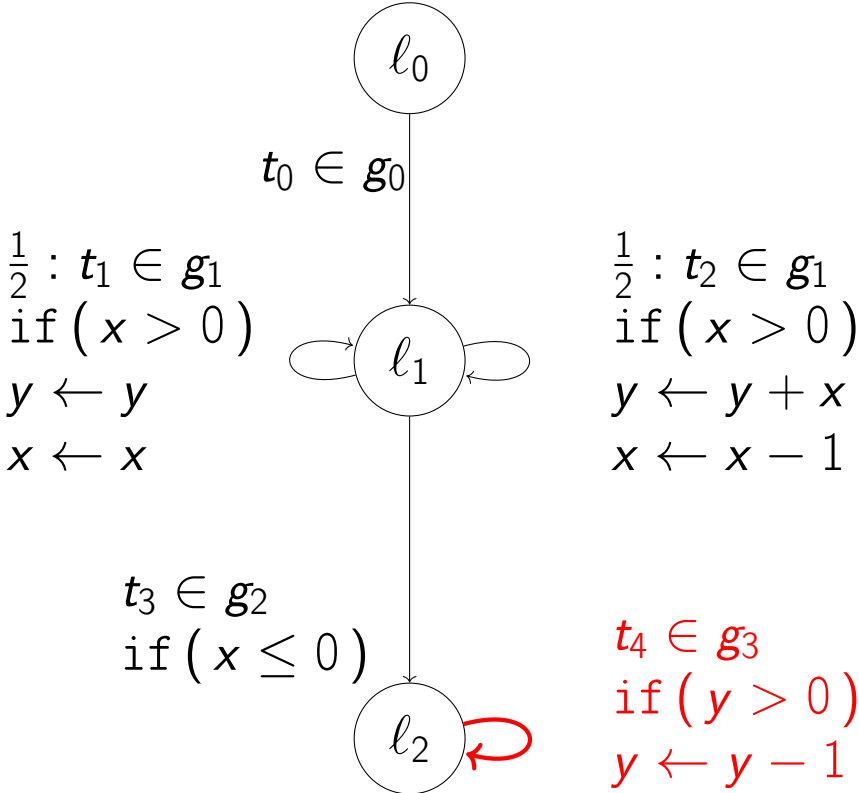
- Given sub-program *GT'* of full program.



Computing Expected Runtime Bounds

Overall Idea

- Given sub-program GT' of full program.
Number of executions of GT' in run of full program?



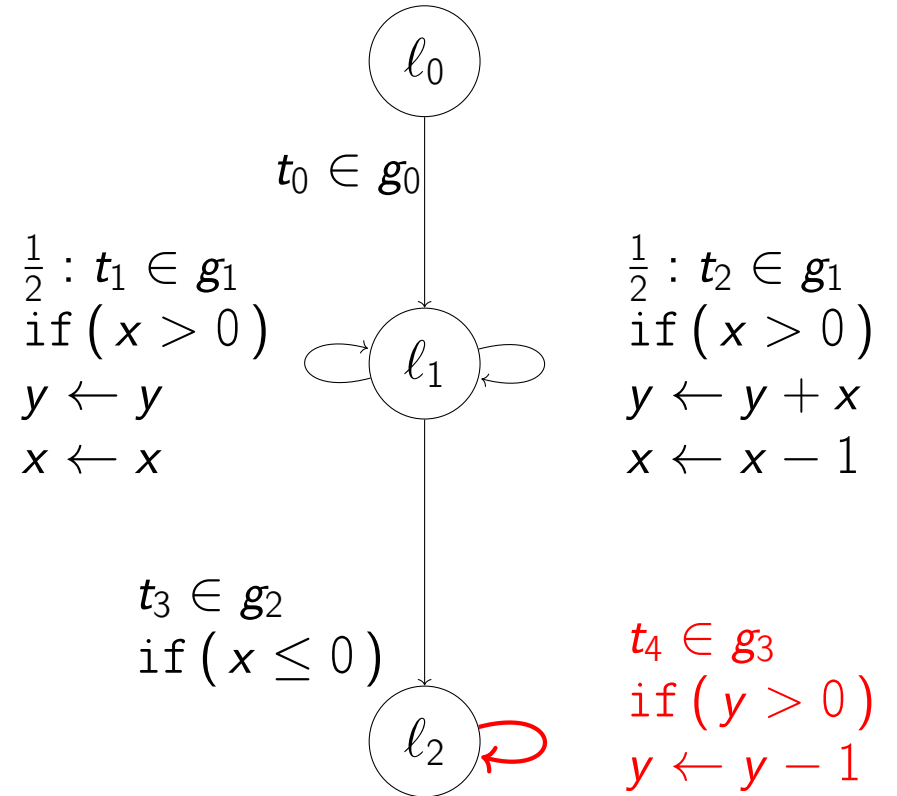
Computing Expected Runtime Bounds

Overall Idea

- Given sub-program GT' of full program.

Number of executions of GT' in run of full program?

$$\leq (\# \text{ enter } (GT')) \cdot (\text{local-runtime}(GT') [v / \text{"size"}_{\text{enter } GT'}(v)])$$



Computing Expected Runtime Bounds

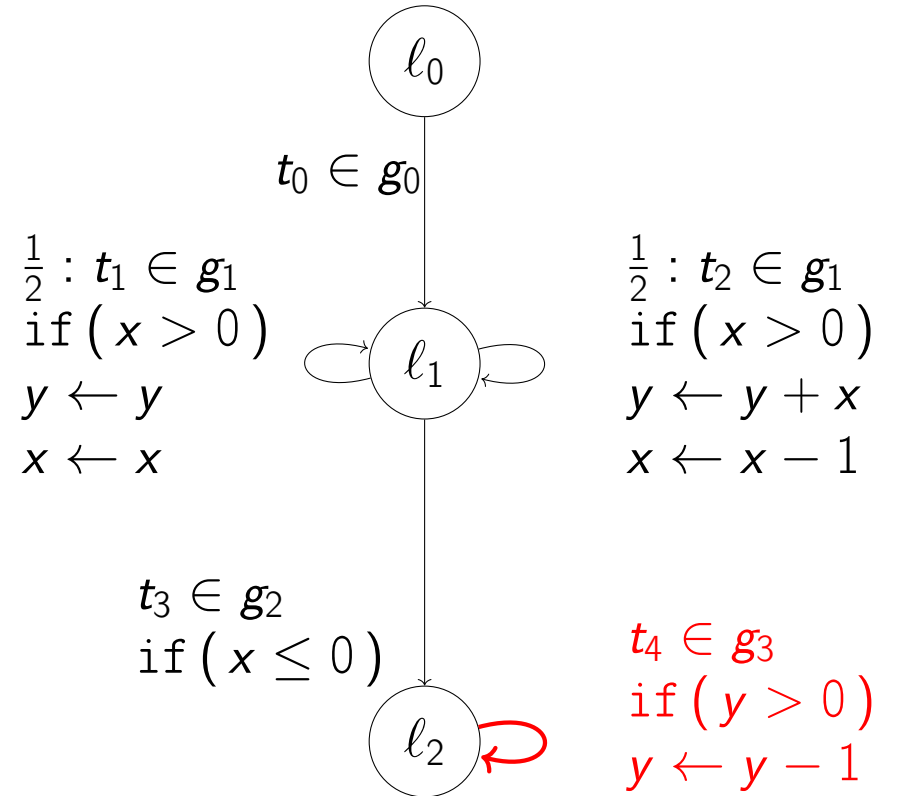
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Expected number of executions of GT' ?



Computing Expected Runtime Bounds

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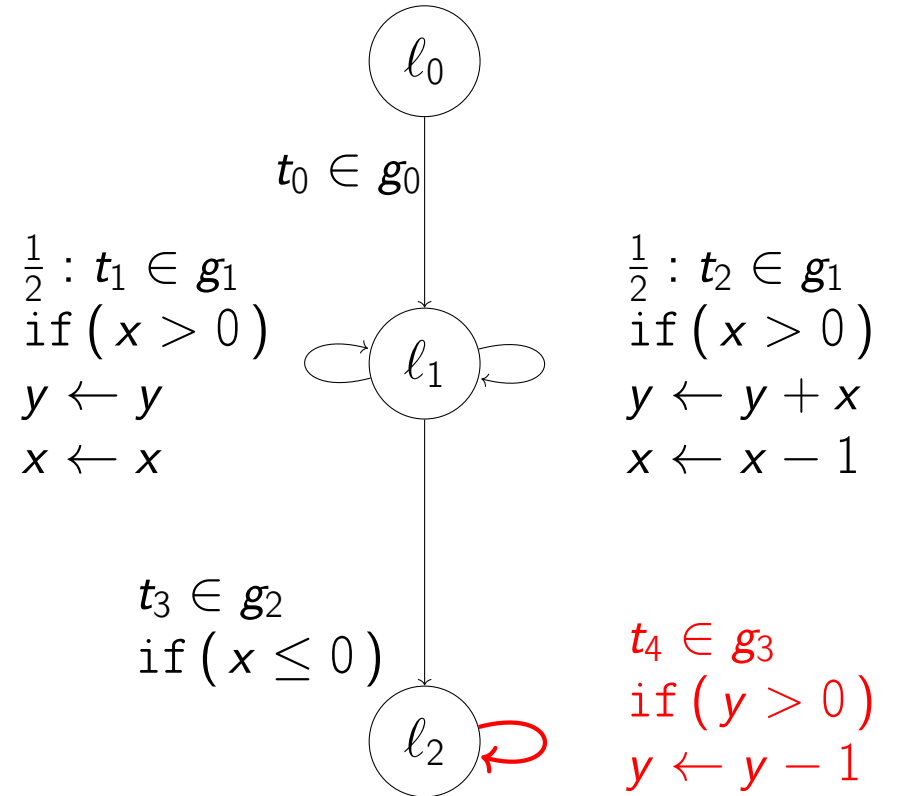
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$$\leq (\# \text{ enter } (GT')) \cdot (\text{local-runtime}(GT') [v / \text{"size"}_{\text{enter } GT'}(v)])$$

Expected number of executions of GT' ?

$$\leq \mathbb{E} \left((\# \text{ enter } (GT')) \cdot (\text{local-runtime}(GT') [v / \text{"size"}_{\text{enter } GT'}(v)]) \right)$$



Computing Expected Runtime Bounds

Overall Idea

- Given sub-program GT' of full program.

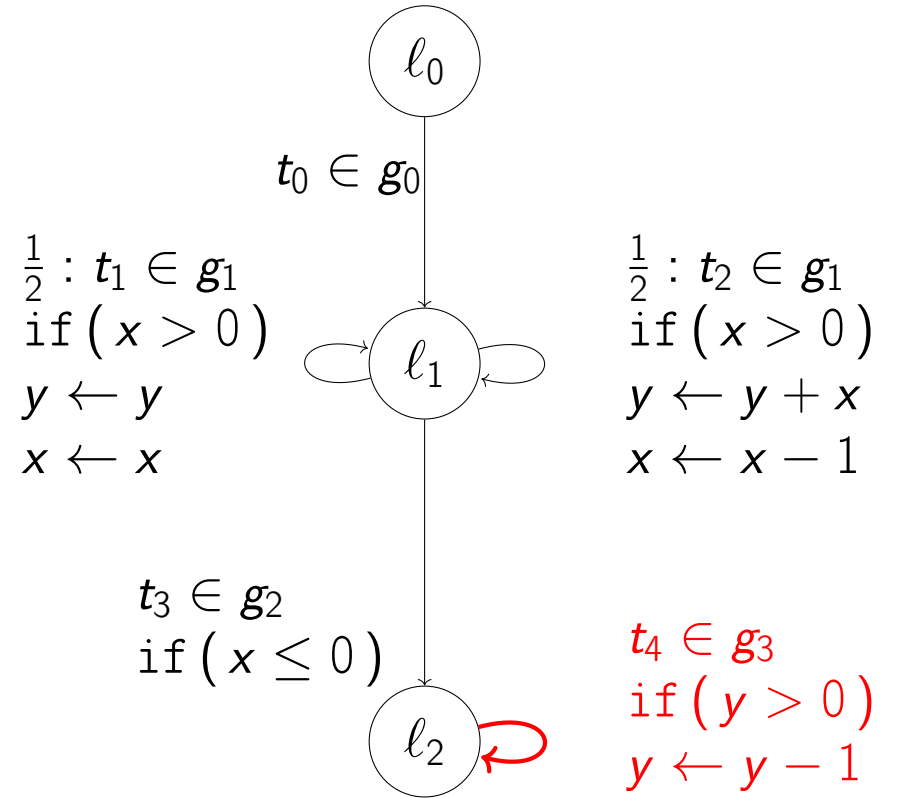
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- How to over-approximate this expected value?



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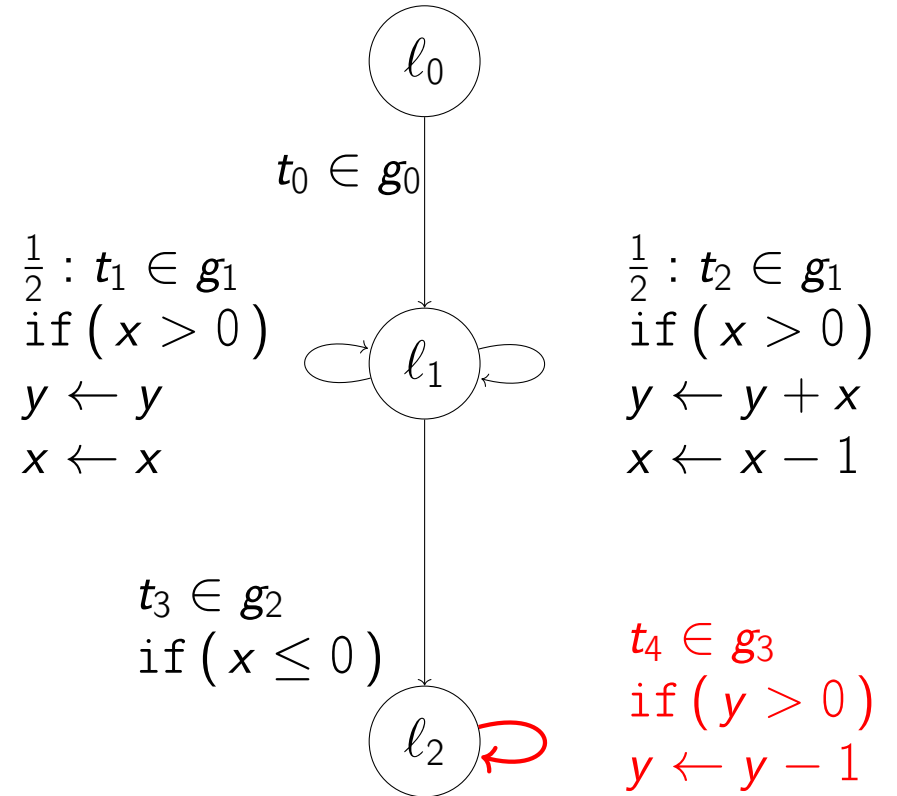
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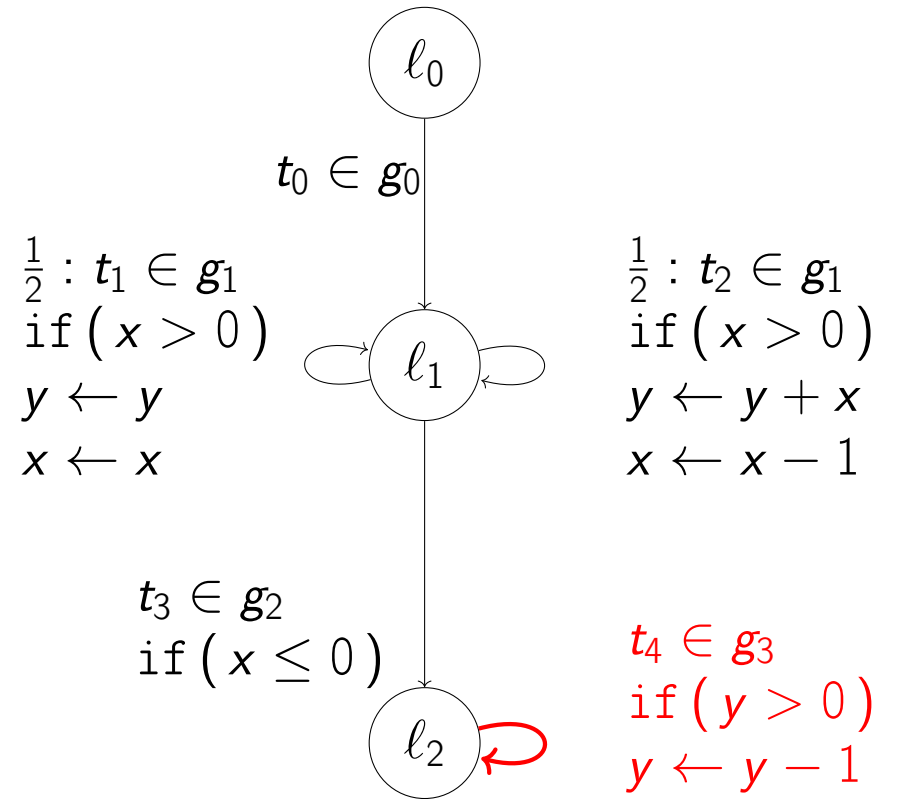
→ Expected value is **not** multiplicative.



Computing Expected Runtime Bounds

Computation

$$\mathbb{E}\left(\left(\# \text{ enter } (GT')\right) \cdot \left(\text{local-runtime}(GT') [v / \text{"size"}_{\text{enter } GT'}(v)]\right)\right)$$

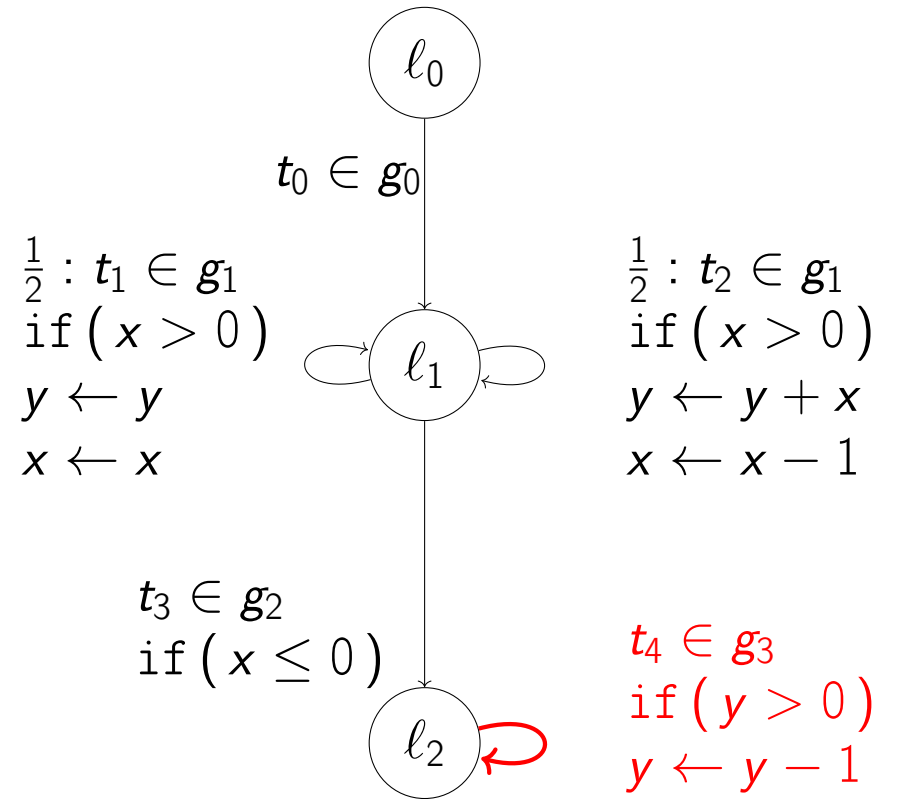


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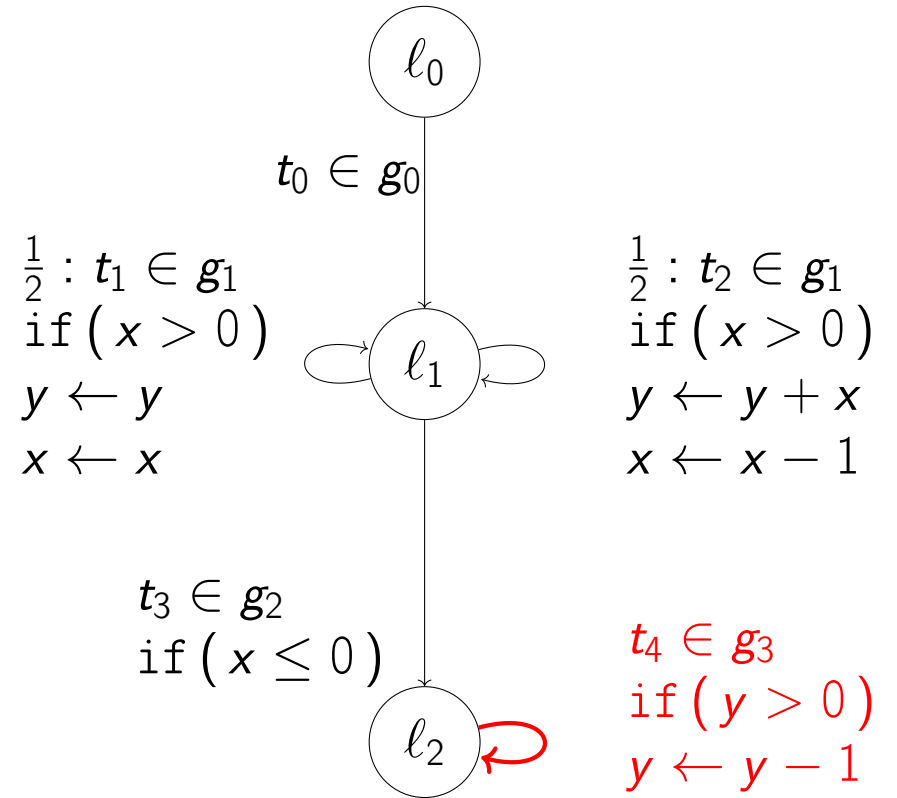
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$\# \text{ enter } (GT')$:



Computing Expected Runtime Bounds

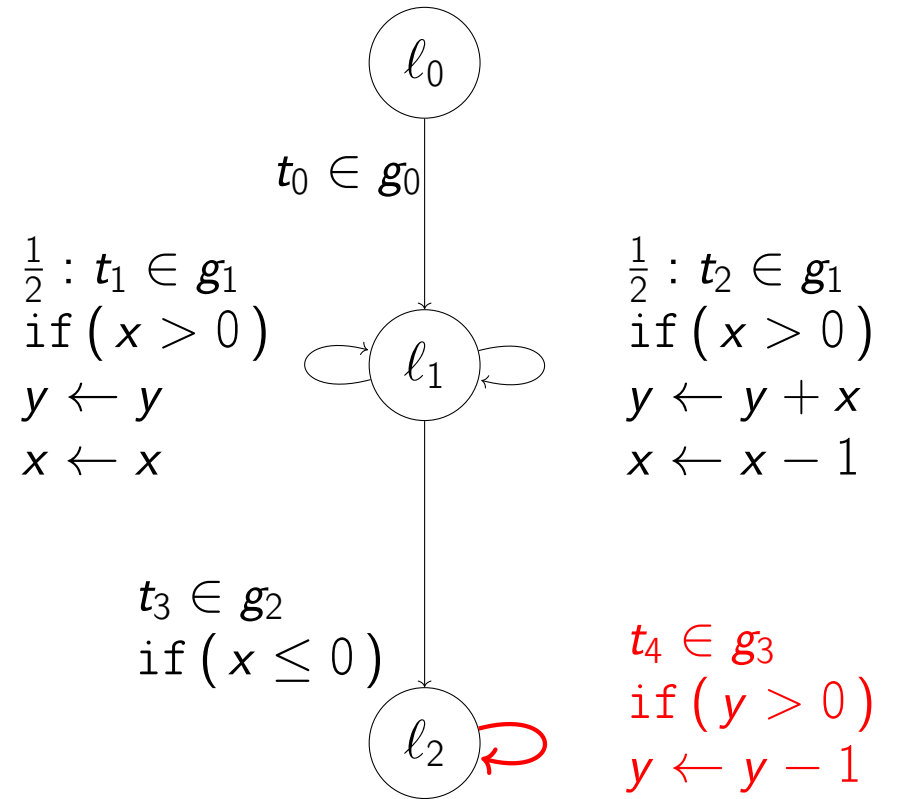
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enter (GT'):

→ Use (classical) worst-case bound from [Giesl et al. '16].



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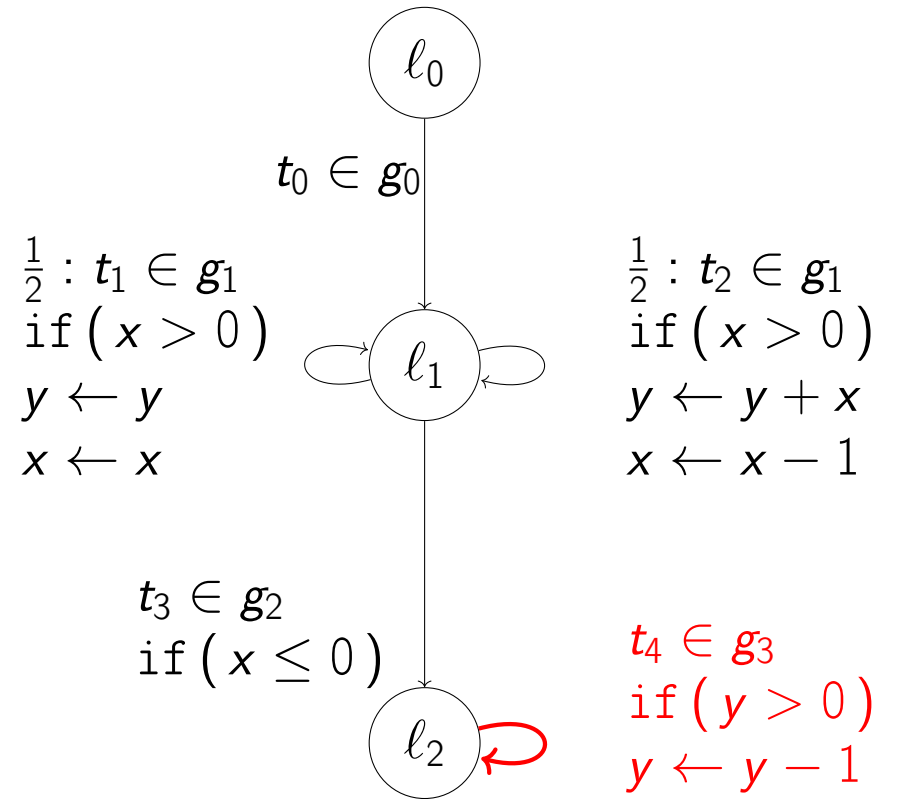
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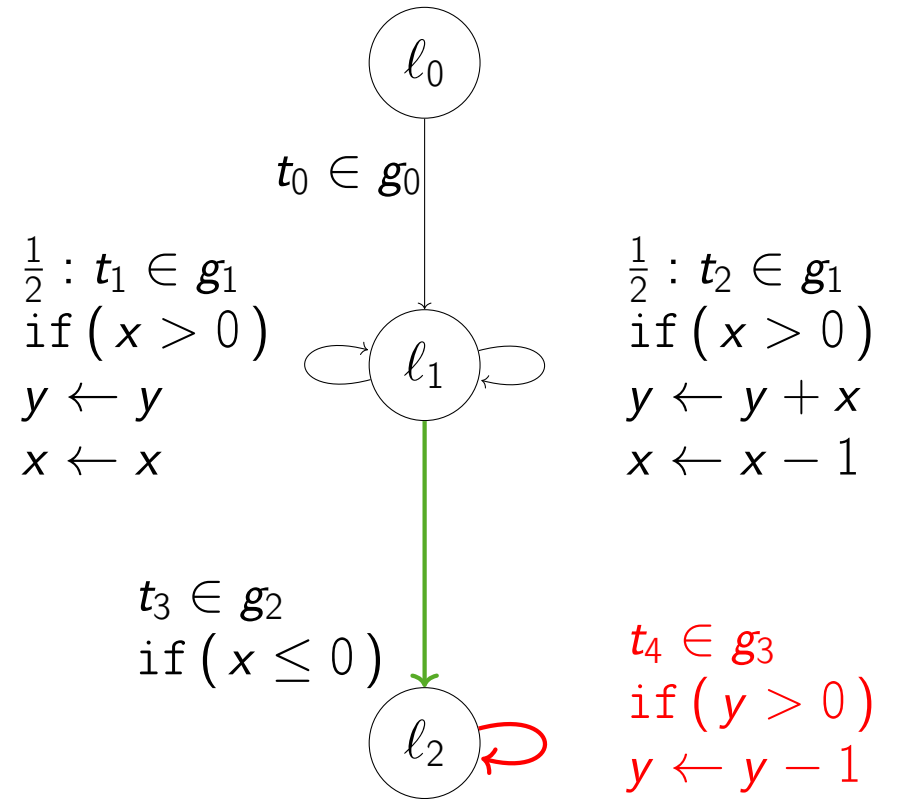
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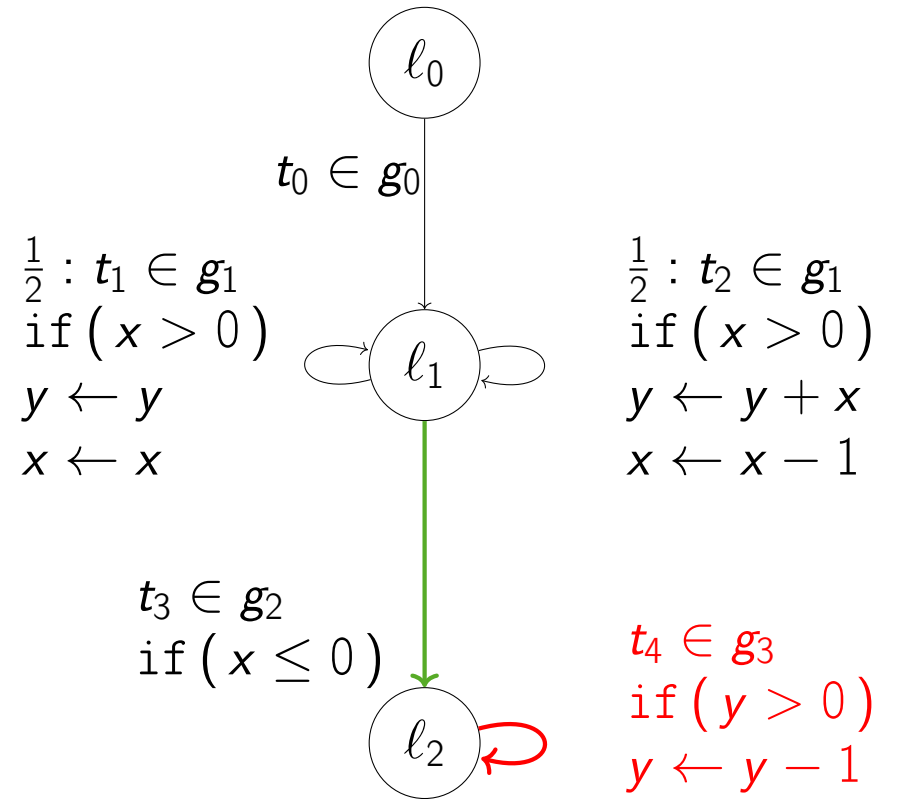
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$\# \text{ enter } (GT')$:

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→ $\# \text{ enter } (GT') = 1$.

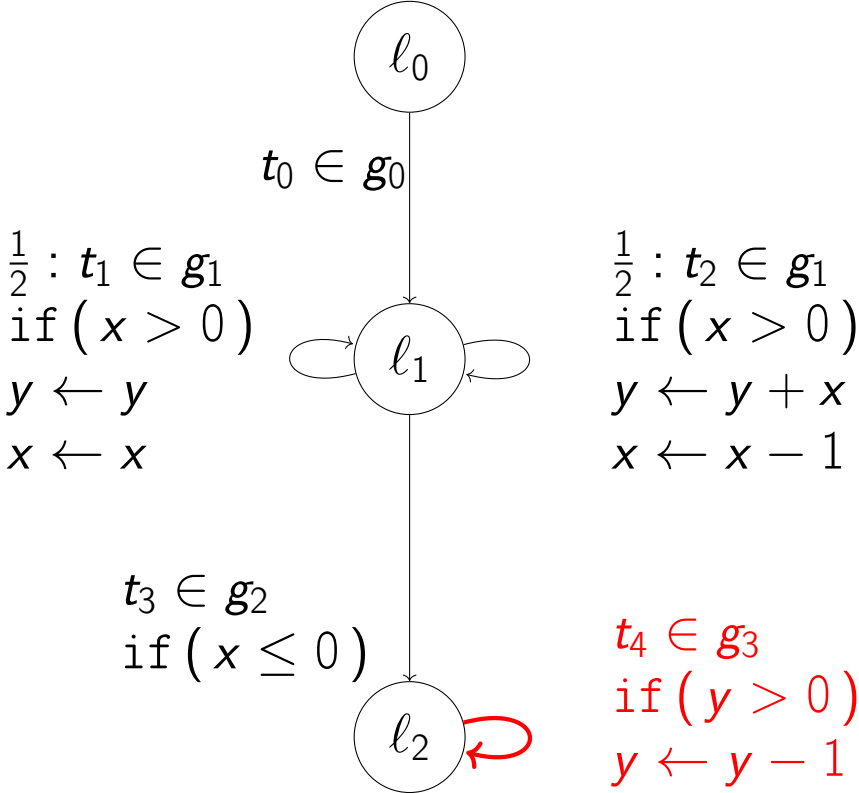


Computing Expected Runtime Bounds

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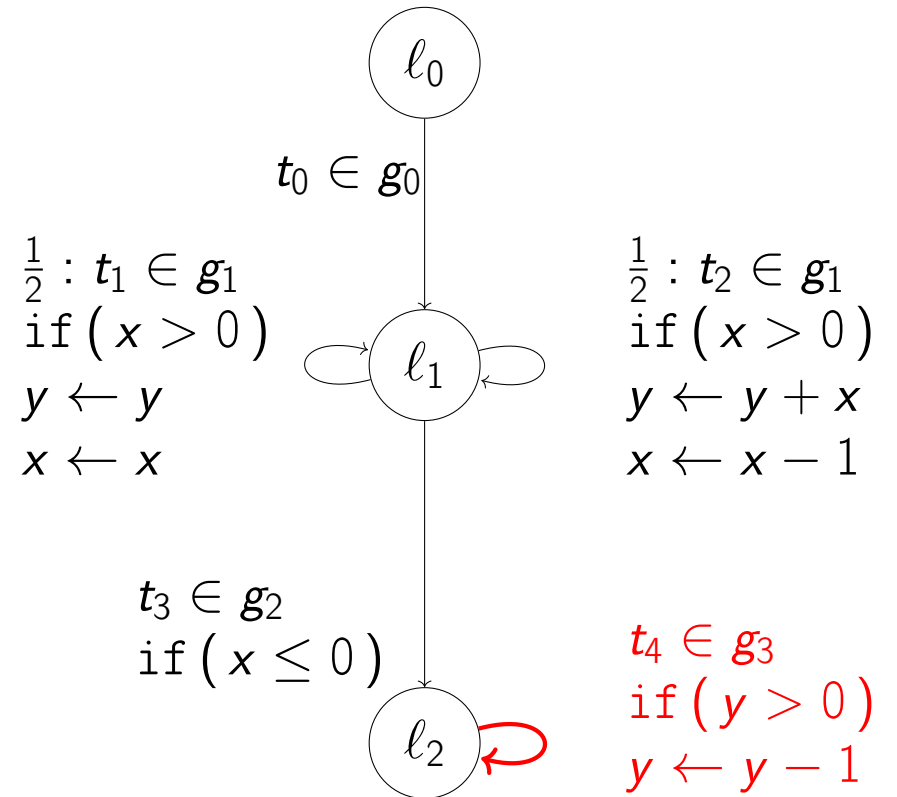
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→ Use **linear** (probabilistic) ranking function τ for GT' .

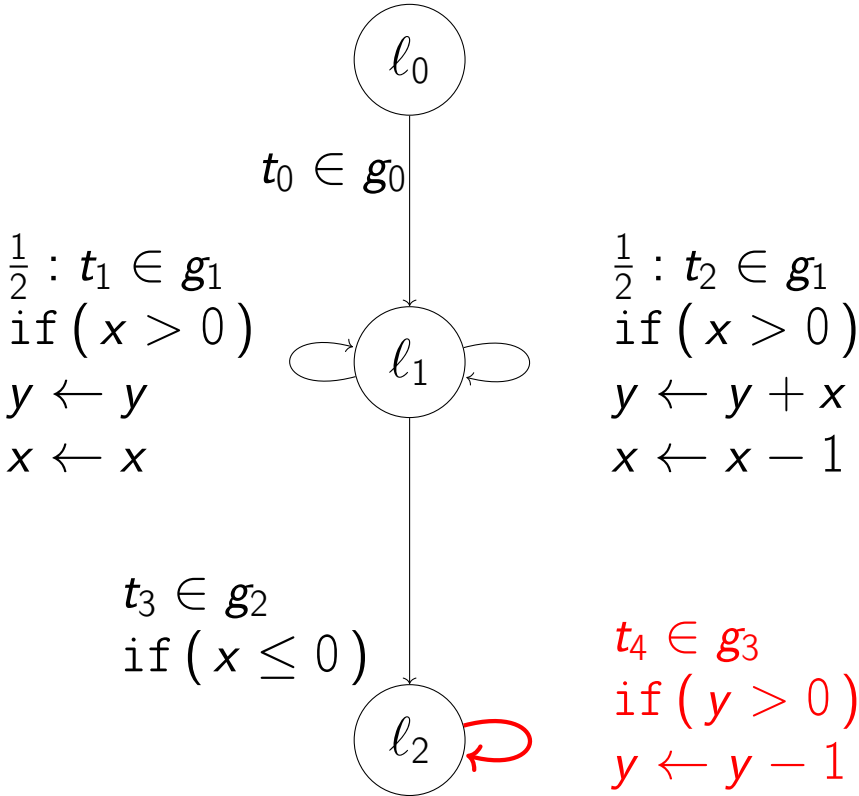


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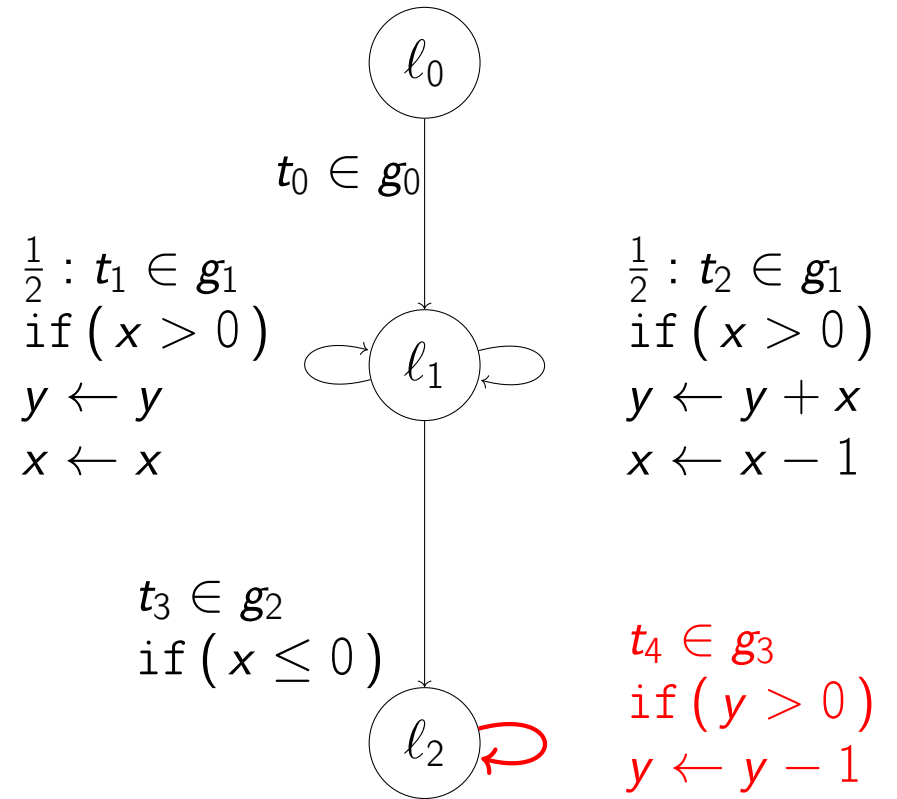


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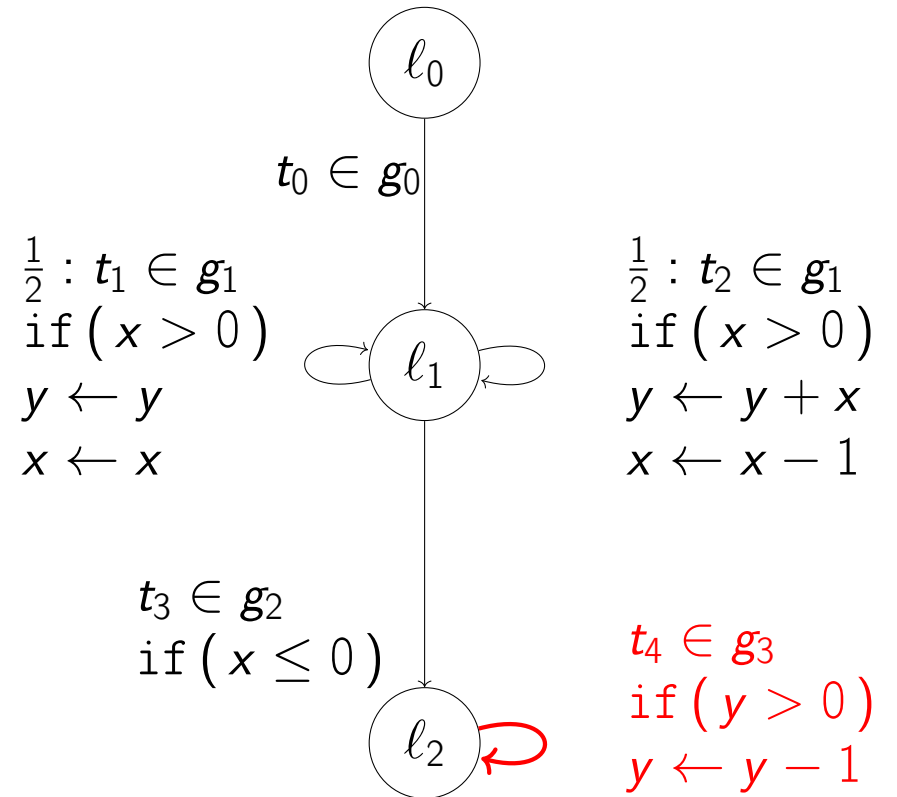


Computing Expected Runtime Bounds

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$$y \left[y / \mathbb{E}(\text{"size"}_{\text{enter } GT'}(y)) \right]$$

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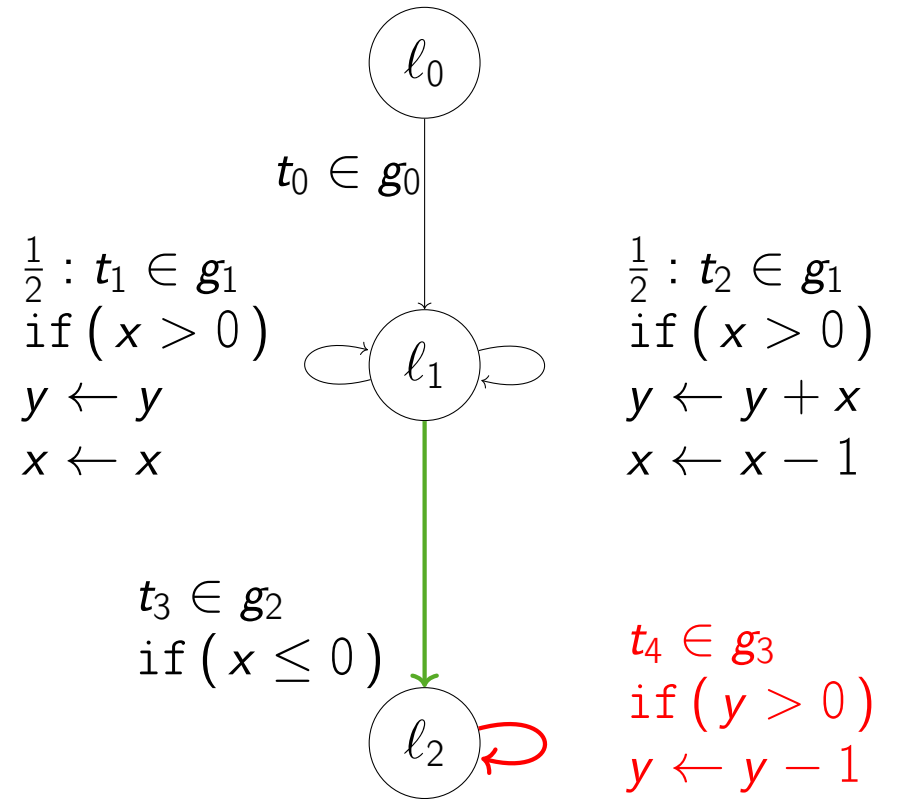


Computing Expected Runtime Bounds

Computation

$$y \left[y / \mathbb{E}(\text{"size"}_{\text{enter } GT'}(y)) \right]$$

- How to over-approximate this expected value?
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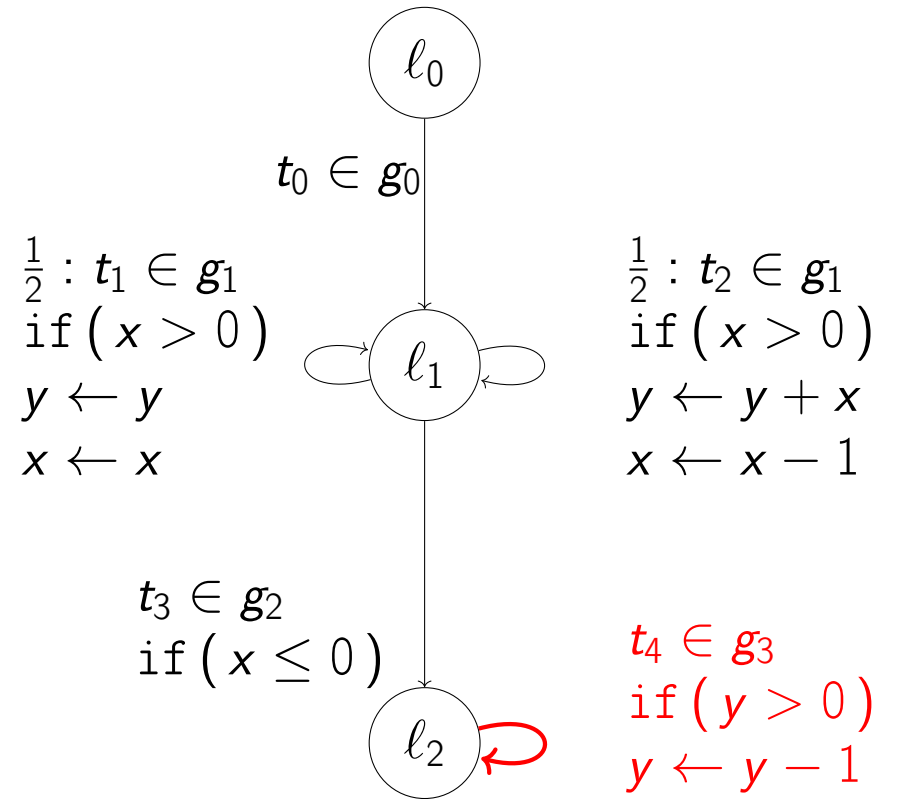


Computing Expected Runtime Bounds

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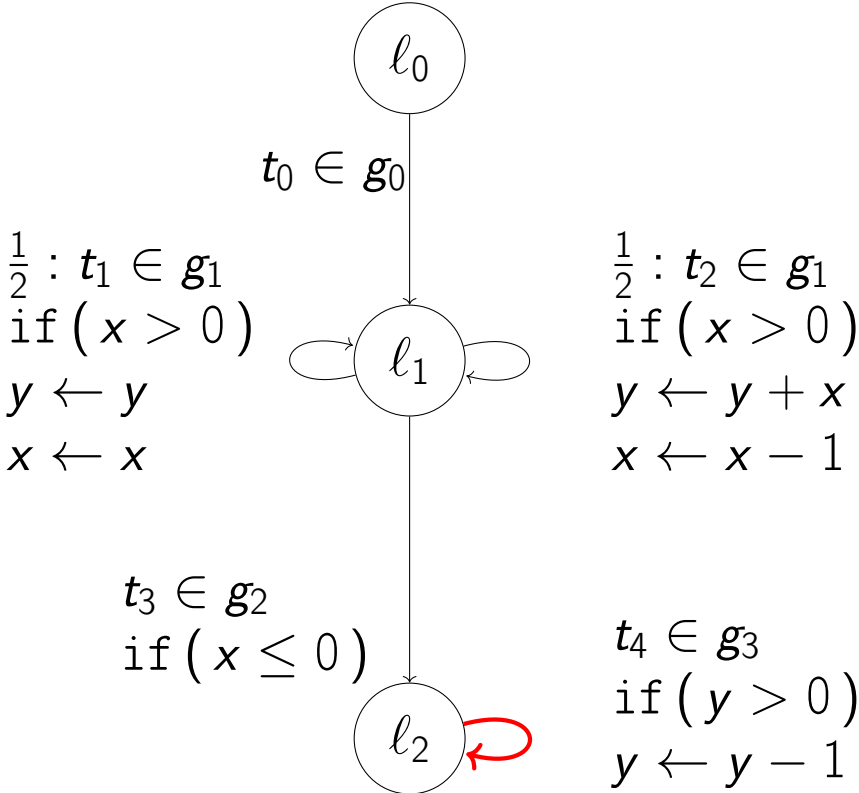
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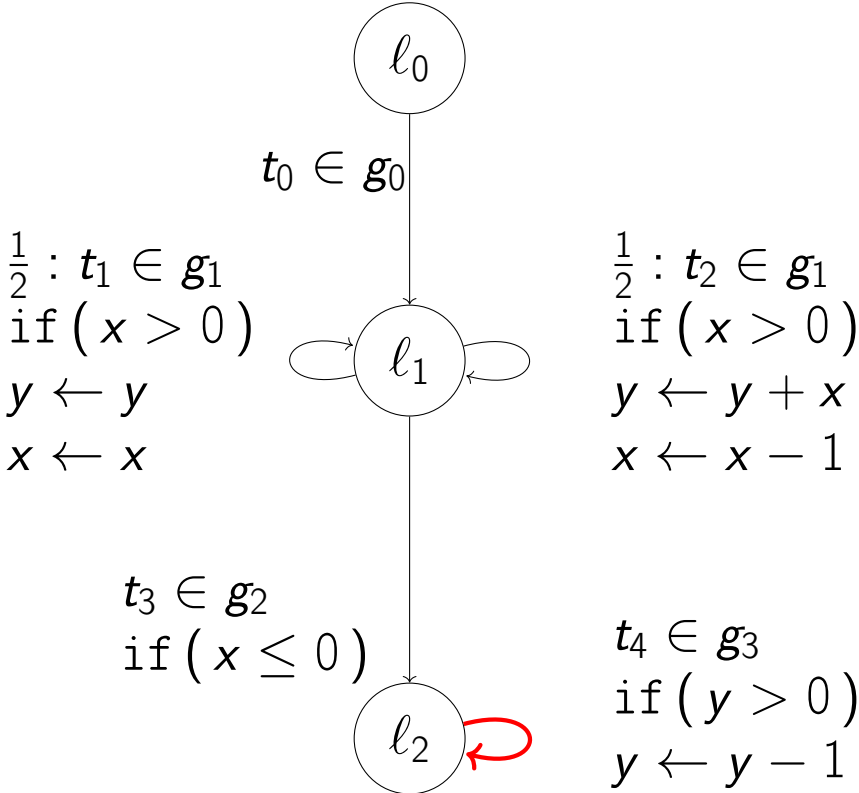
Summary



Computing Expected Runtime Bounds

Summary

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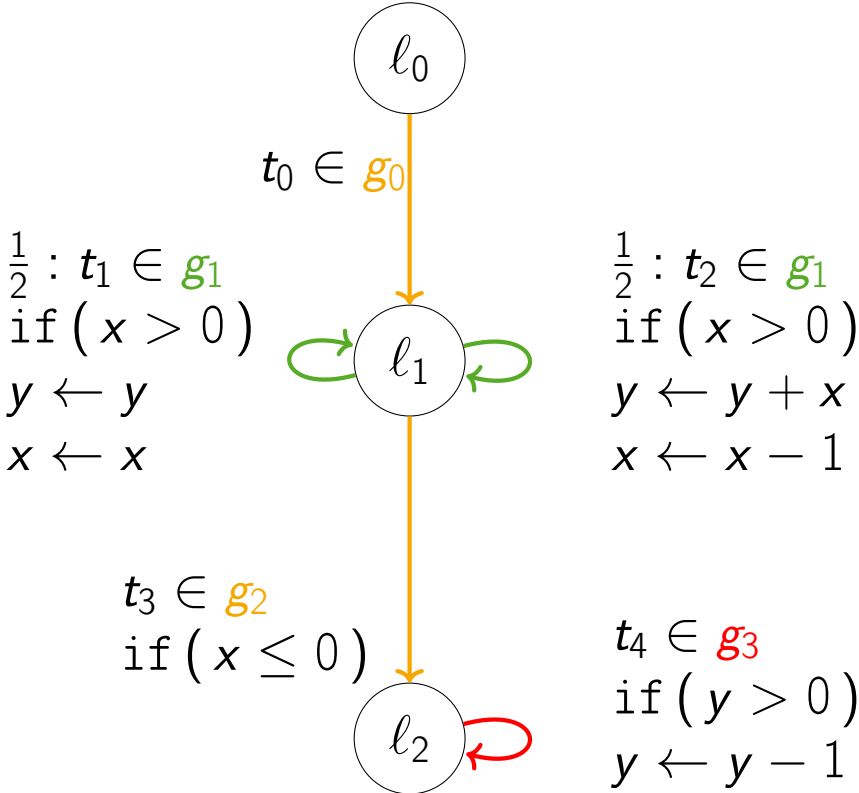


Computing Expected Runtime Bounds

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Overall expected runtime of program:

$$1 + 2 \cdot x_0 + 1 + x_0^2 + y_0$$



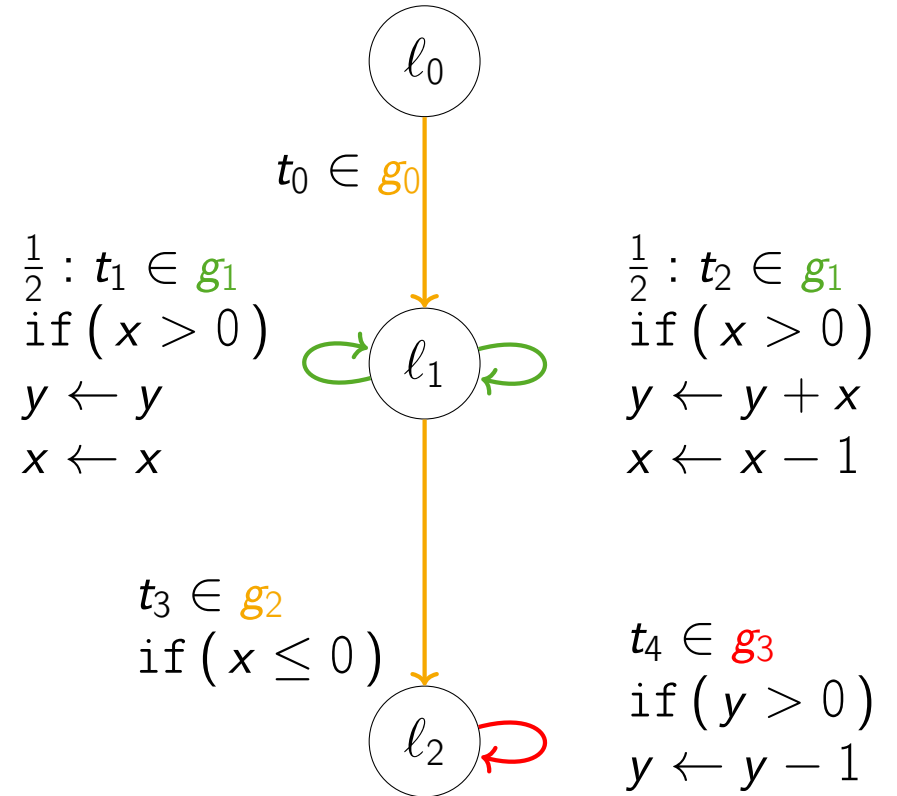
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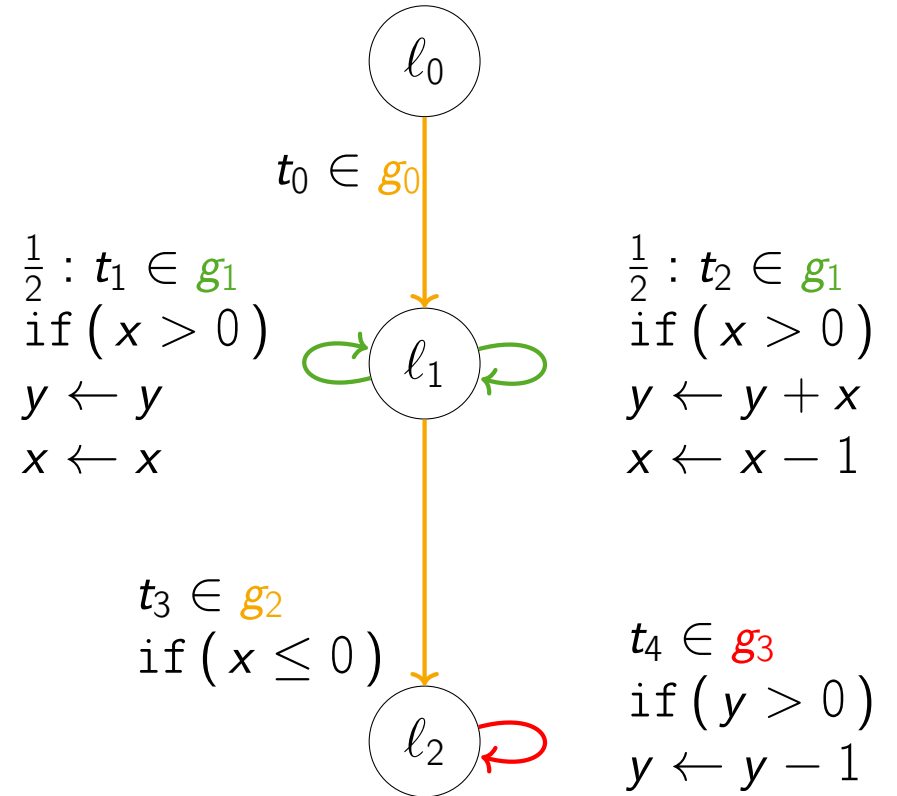
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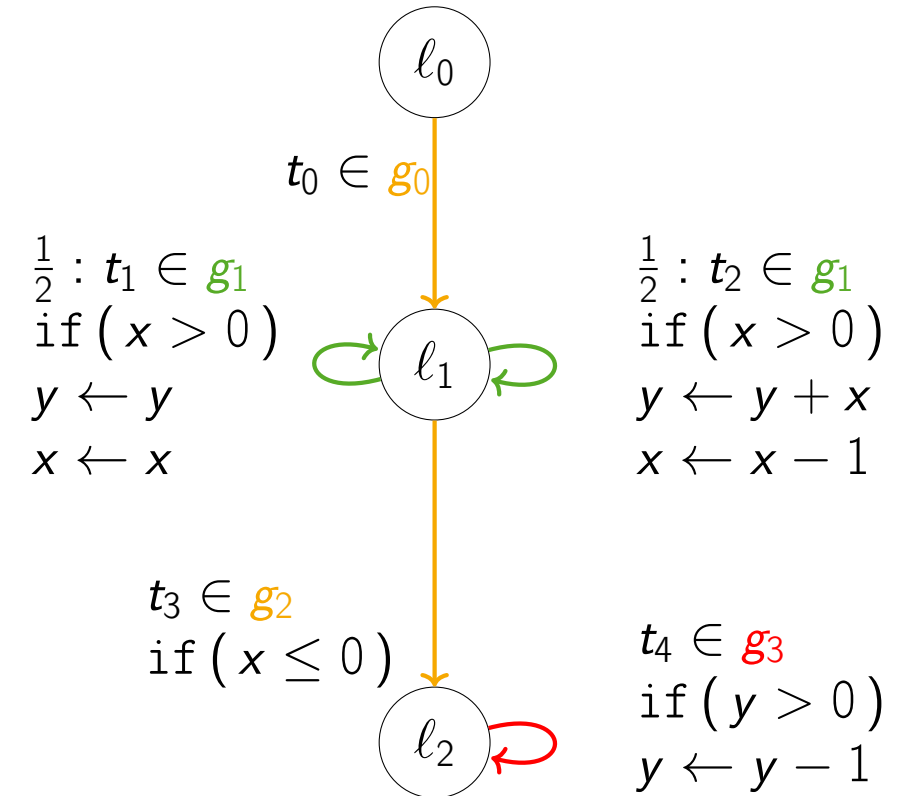
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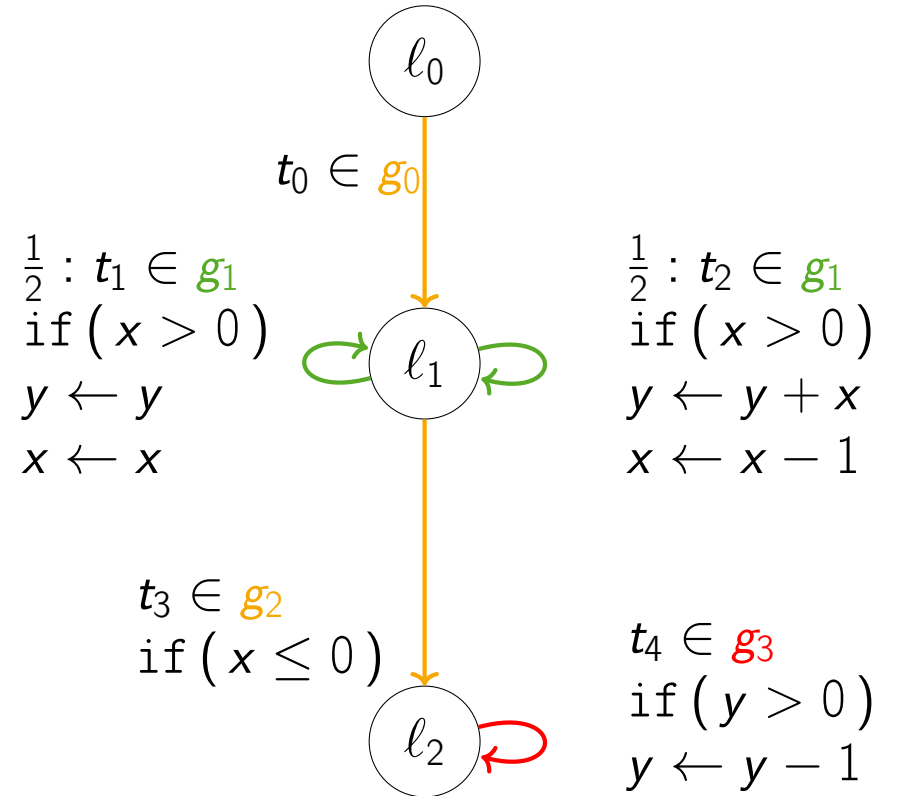
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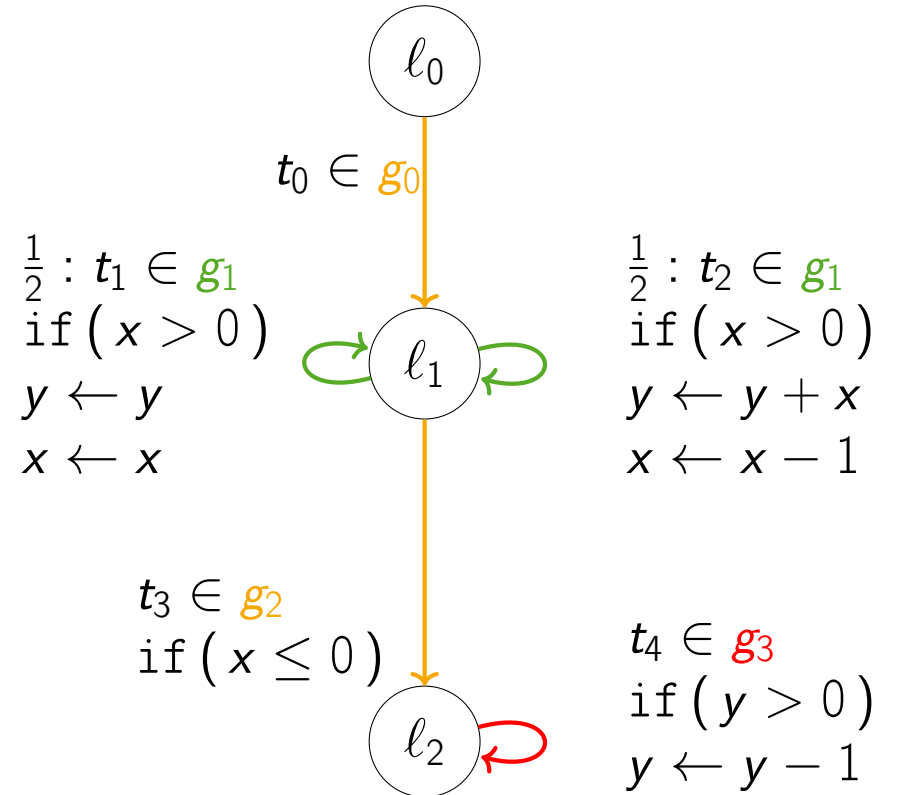
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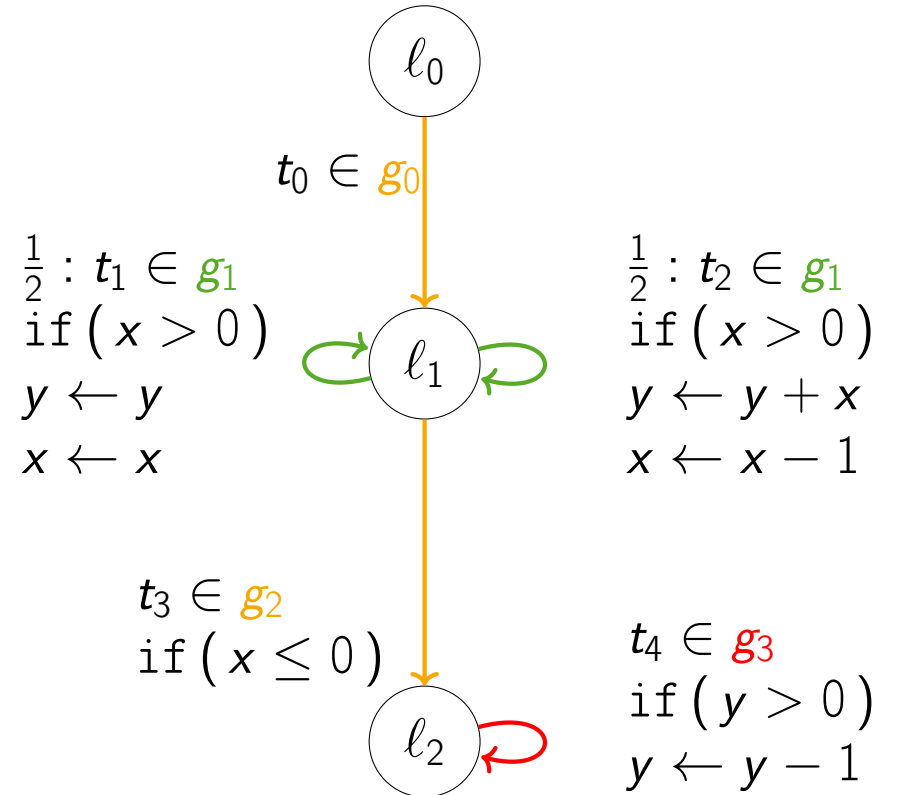
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 - Alternating computation of runtime and size bounds.

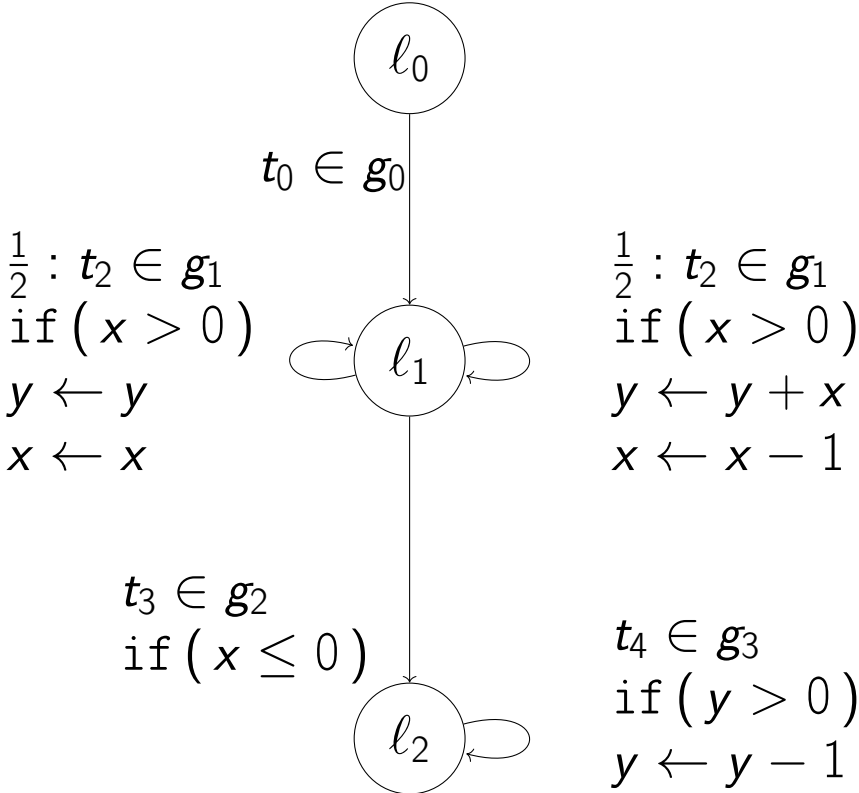


Computing Expected Size Bounds

Overall Idea

Computing Expected Size Bounds

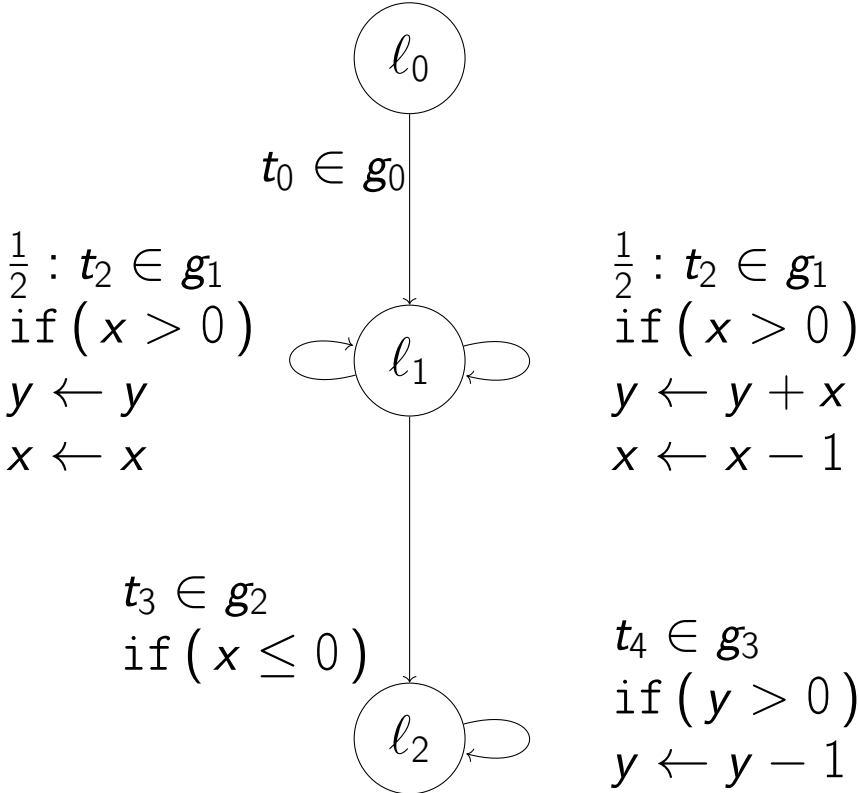
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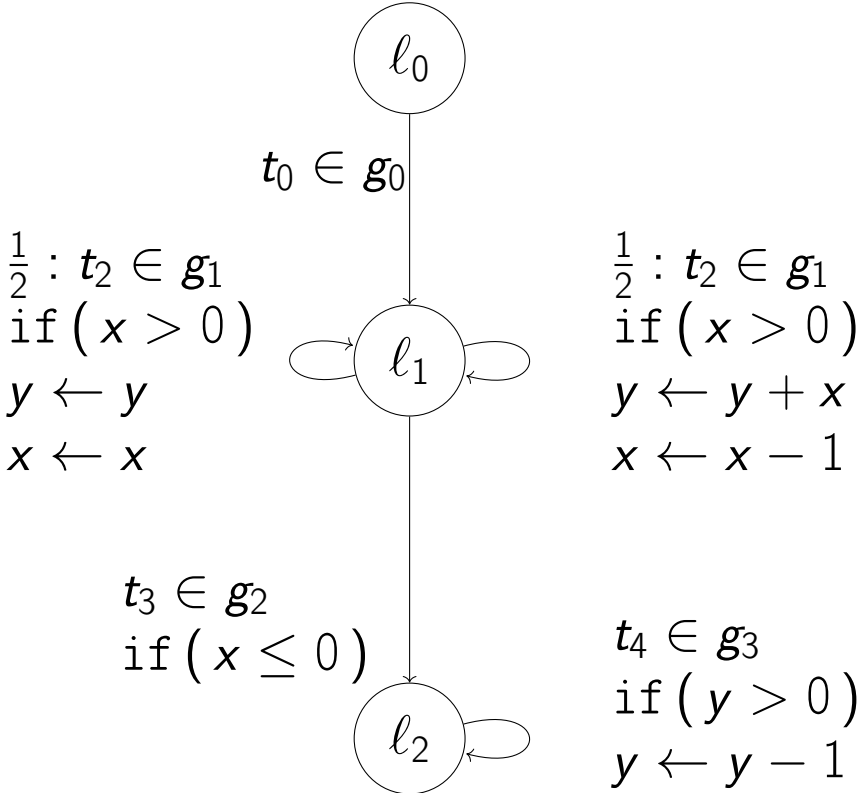
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Computing Expected Size Bounds

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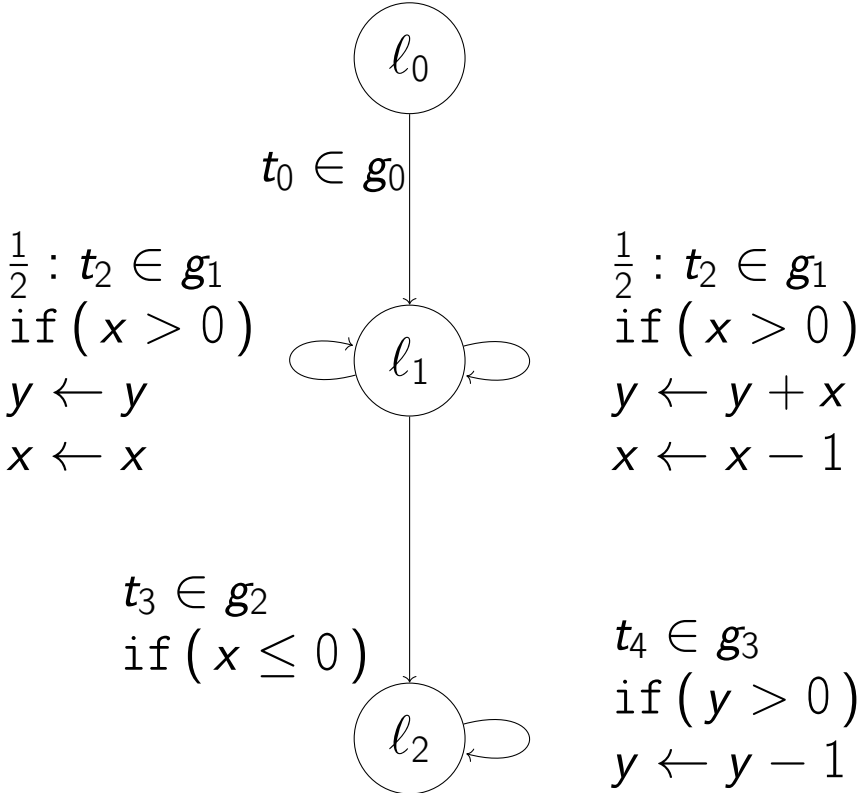
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Computing Expected Size Bounds

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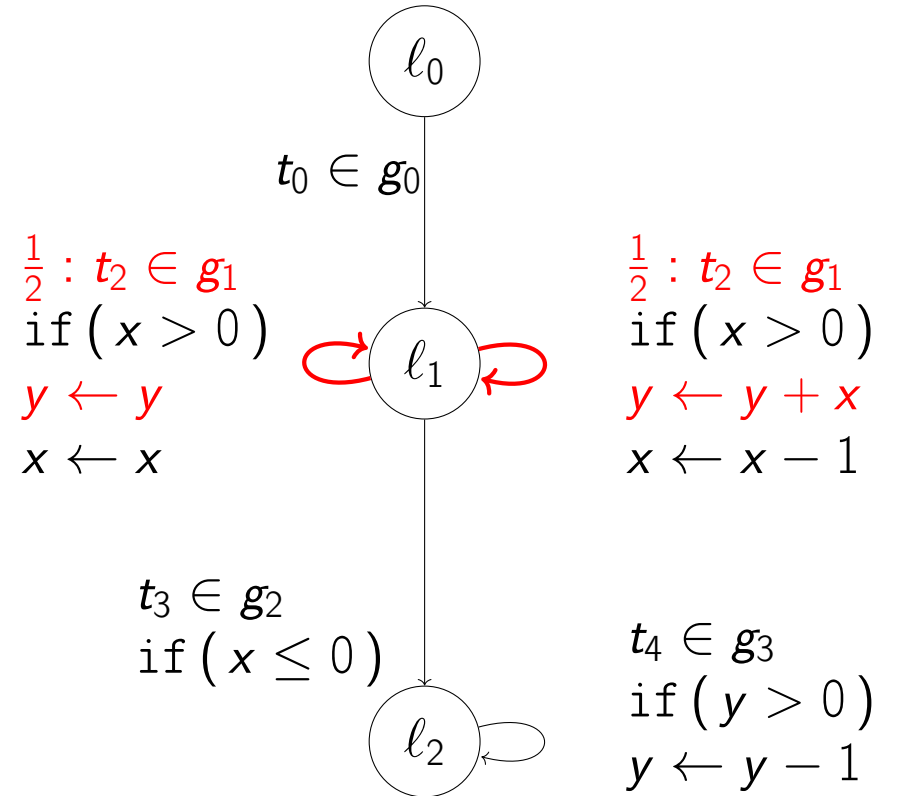
- What means “size”?
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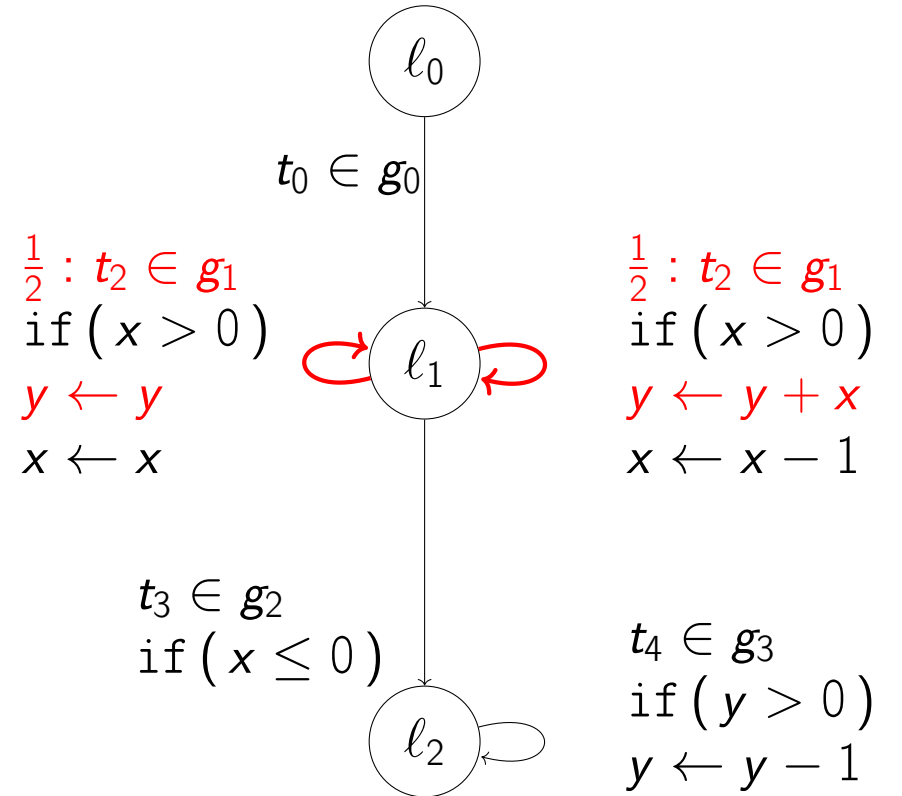
- What means “size”?
 - $\mathcal{S}(g_1, y)$ largest value y takes after execution of g_1
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Computing Expected Size Bounds

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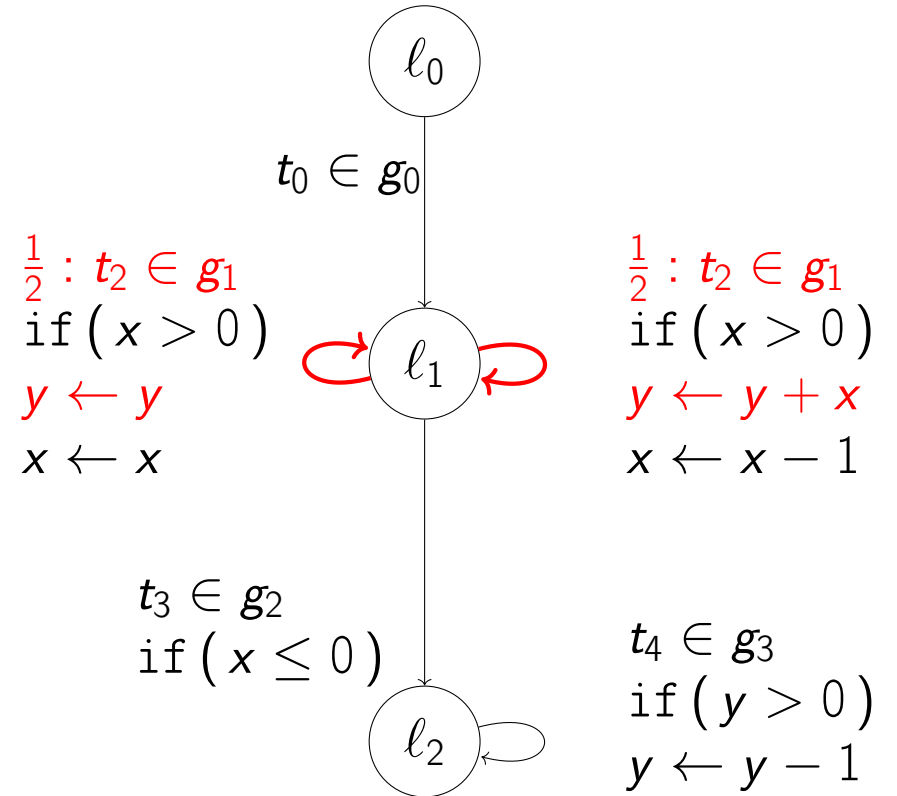
Expected size $\mathbb{E}(\mathcal{S}(g_1, y))$:



Computing Expected Size Bounds

Overall Idea

$$\begin{aligned} \text{Expected size } \mathbb{E}(\mathcal{S}(g_1, y)) : \\ \leq \mathbb{E}(\text{incoming-size}(y) + \mathcal{R}(g_1) \cdot \text{worst-case-change}(g_1, y)) \end{aligned}$$



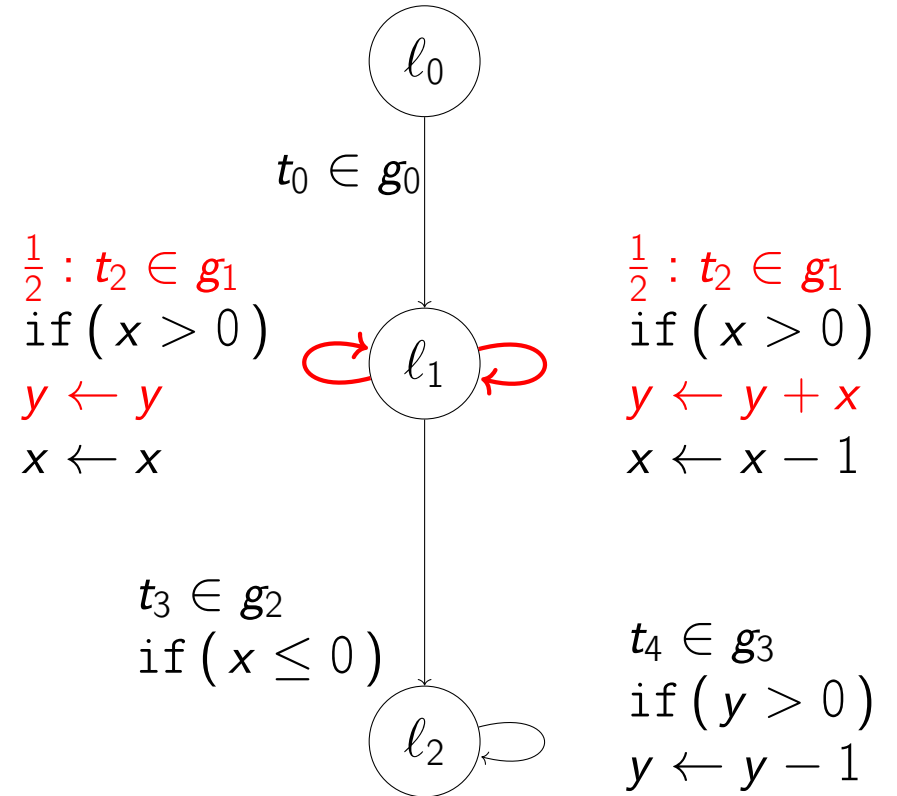
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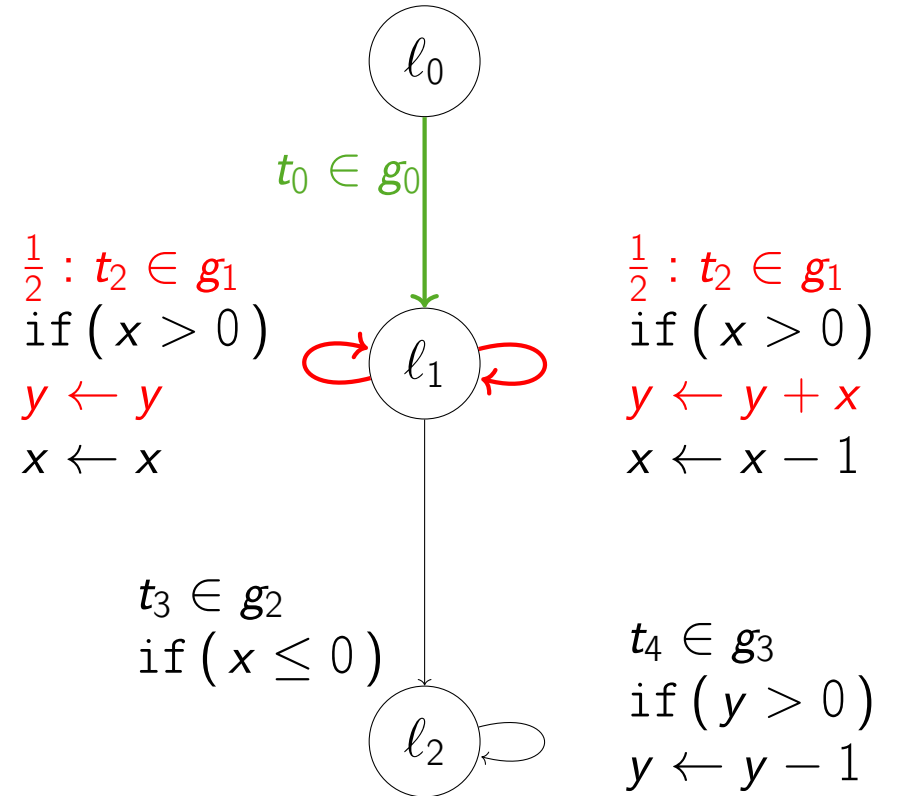
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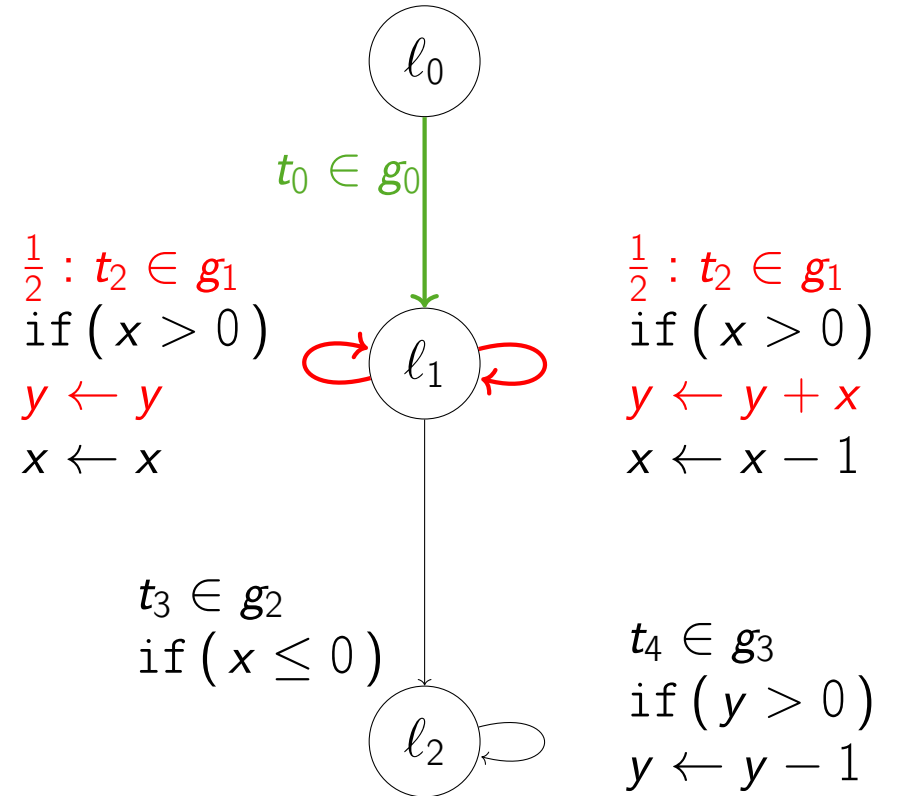
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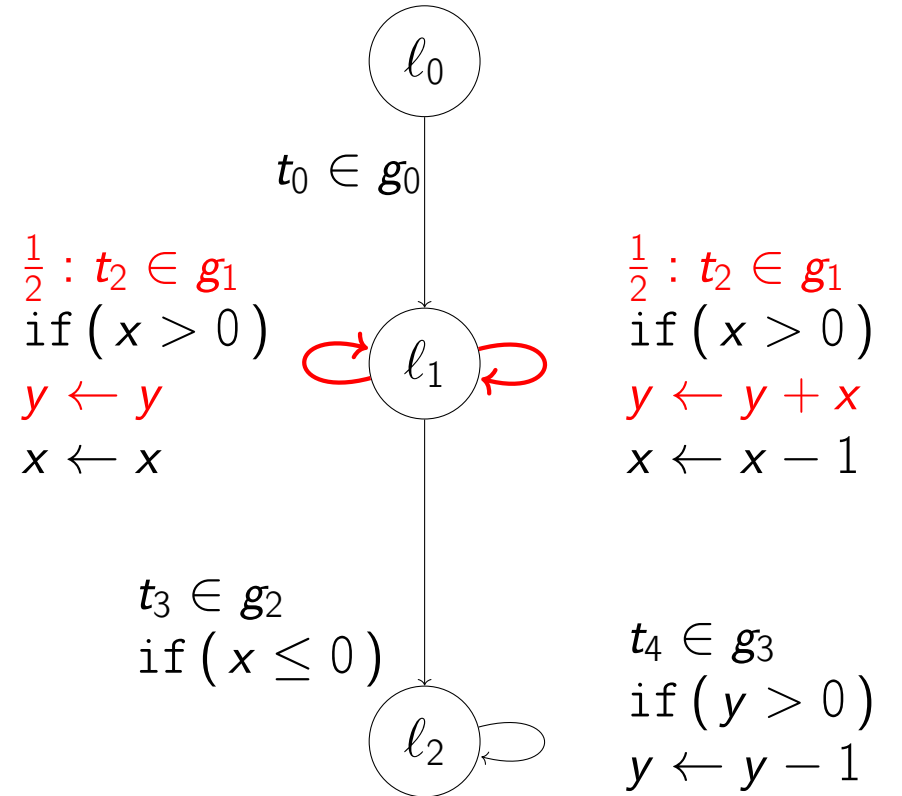
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Computing Expected Size Bounds

Computation

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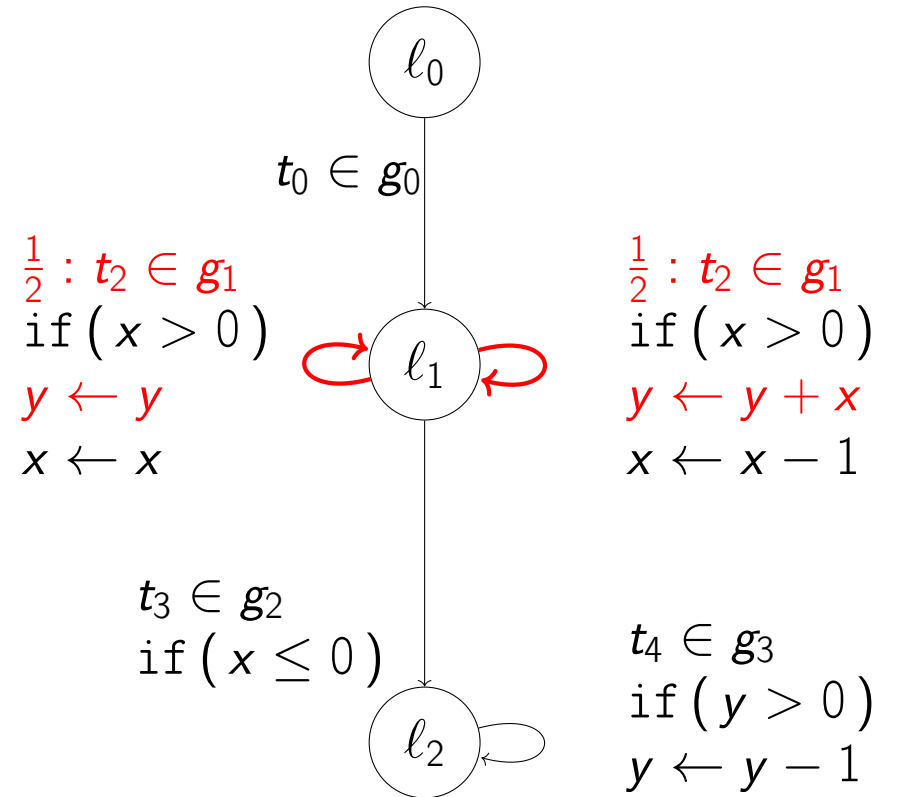
Computing Expected Size Bounds

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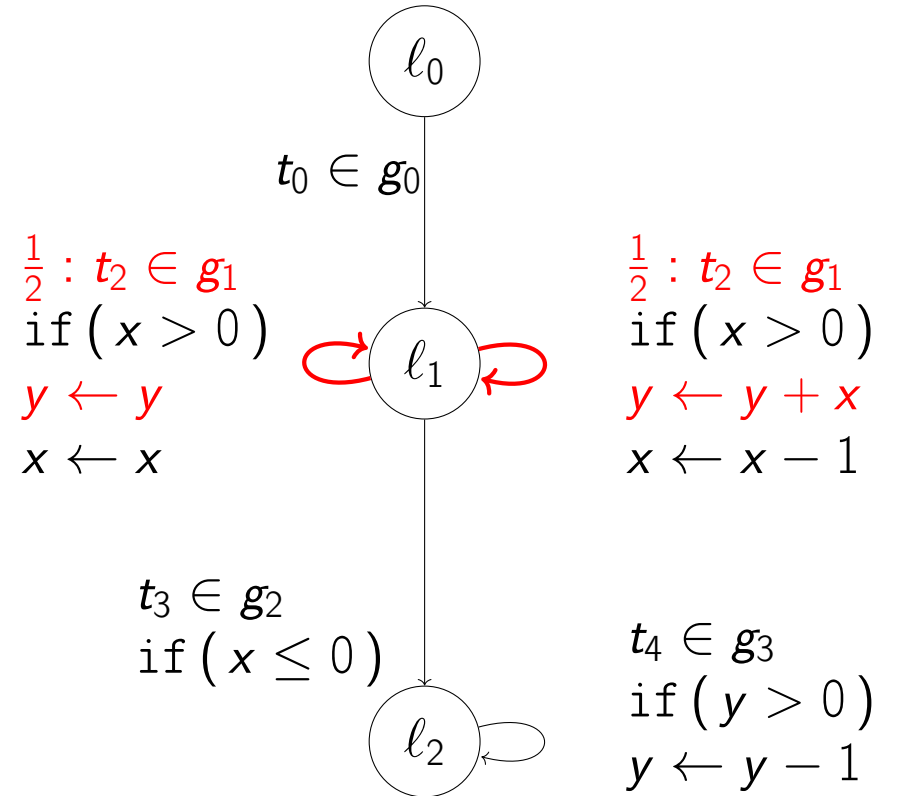
→ worst-case-change is independent of runtime.



Computing Expected Size Bounds

Computation

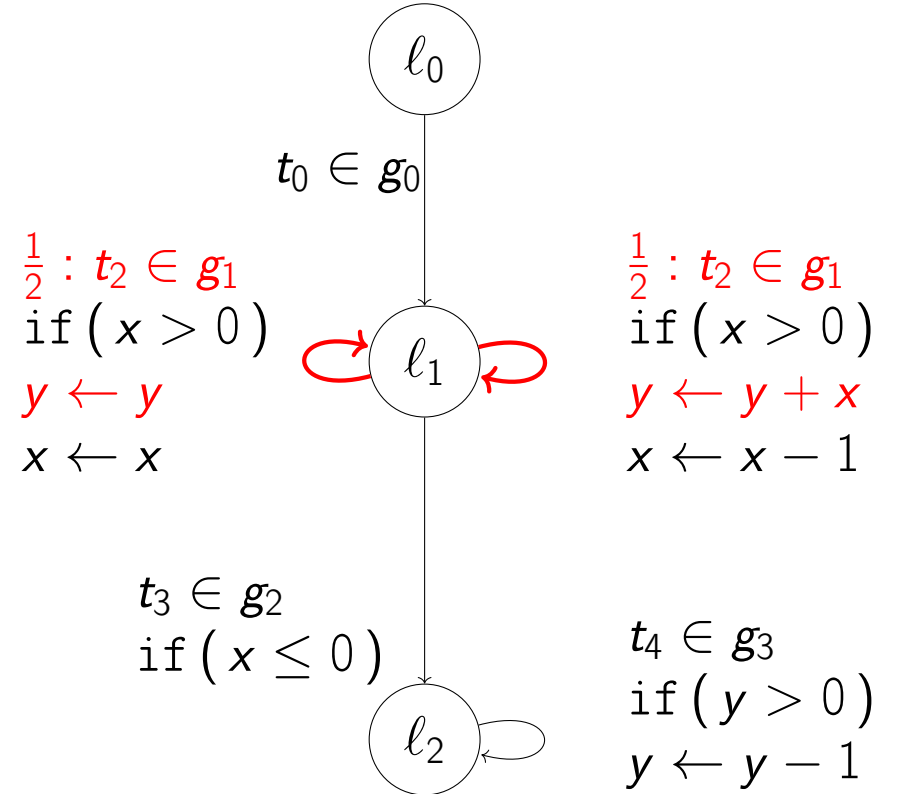
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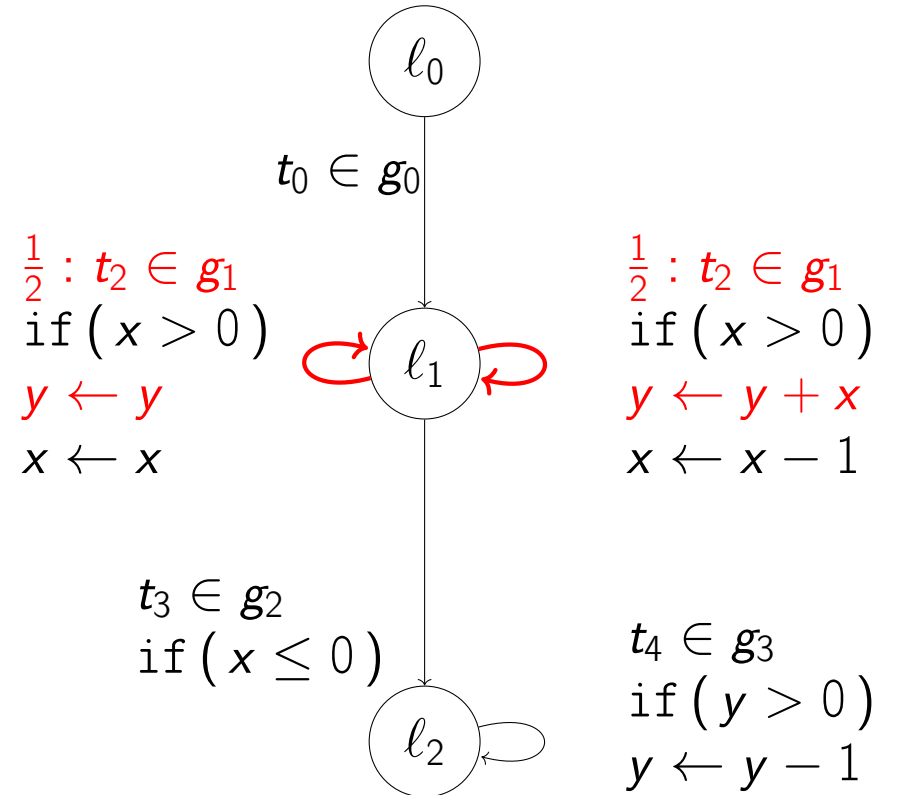
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Computation

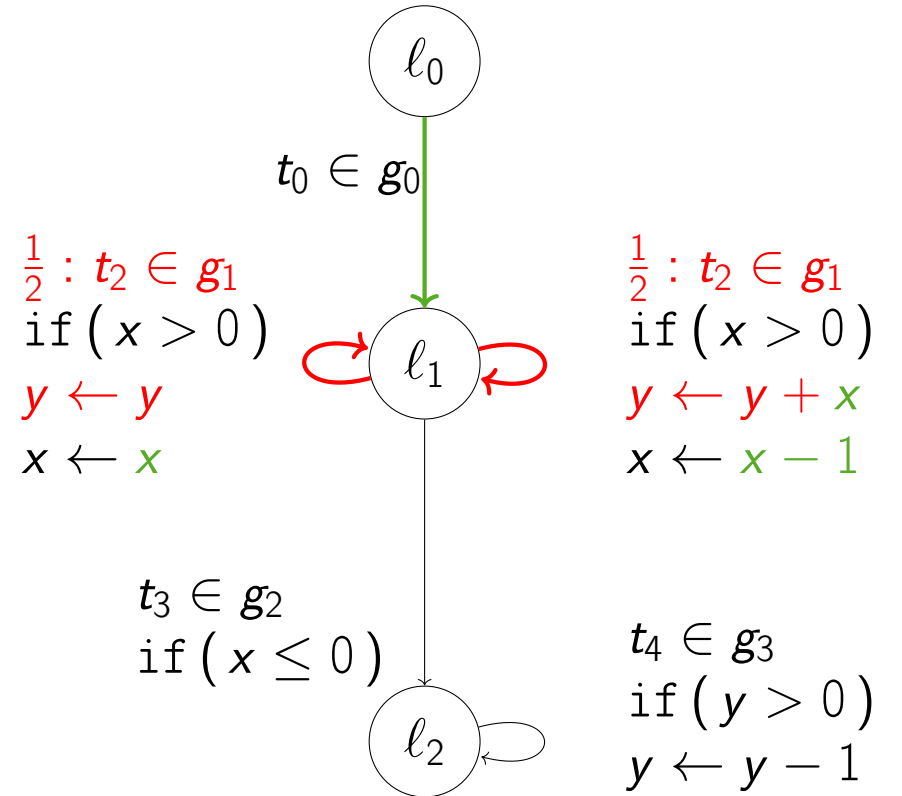
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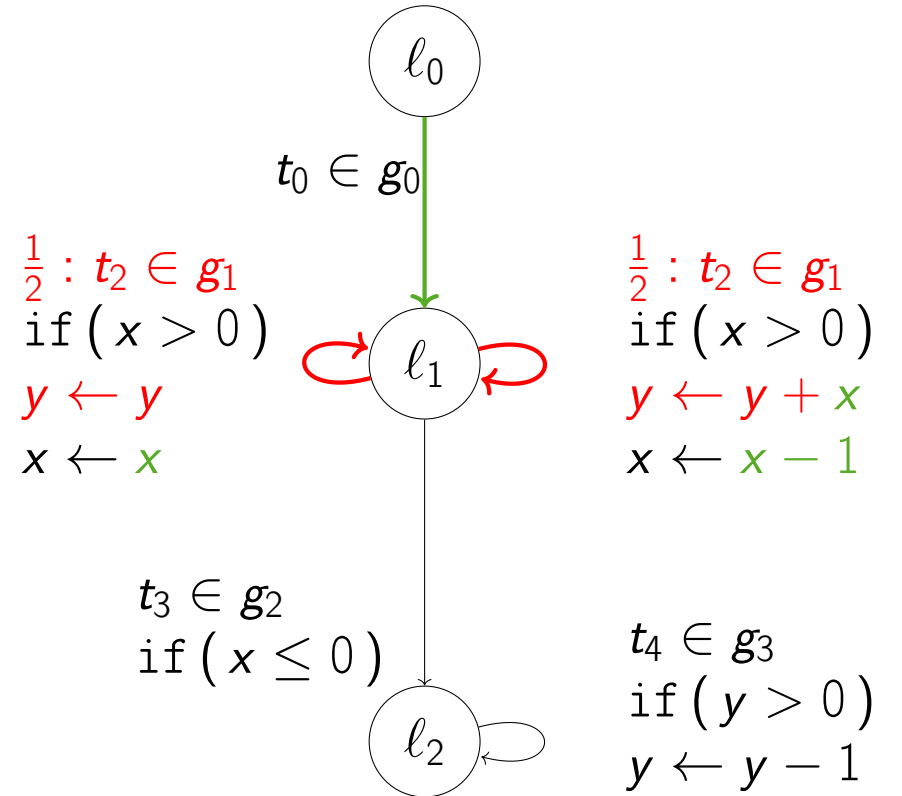
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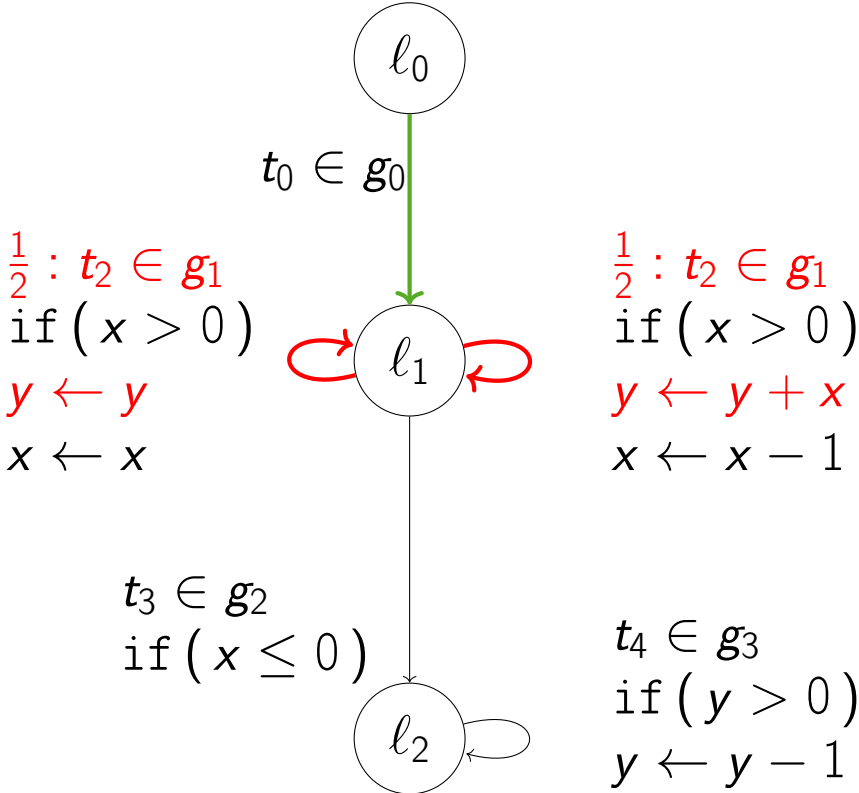
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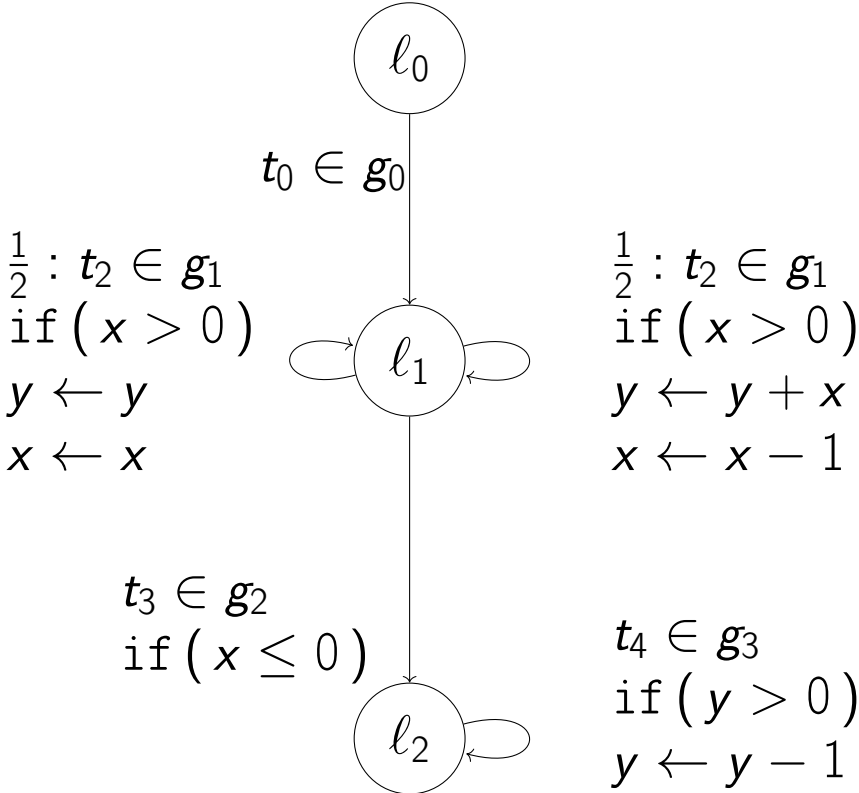
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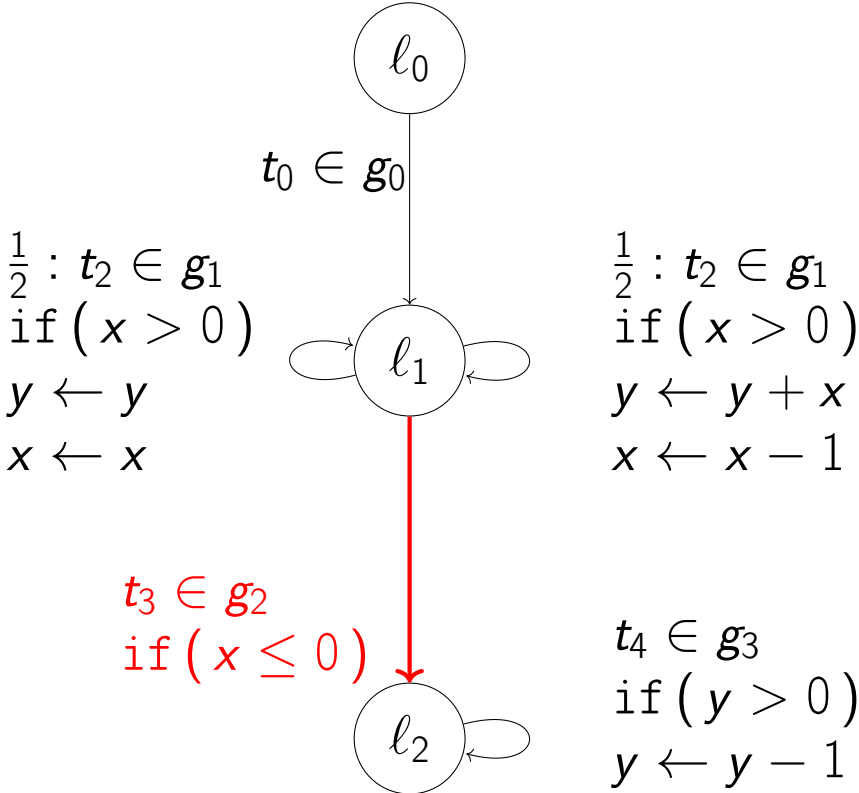
Computing Expected Size Bounds

Computation



Computing Expected Size Bounds

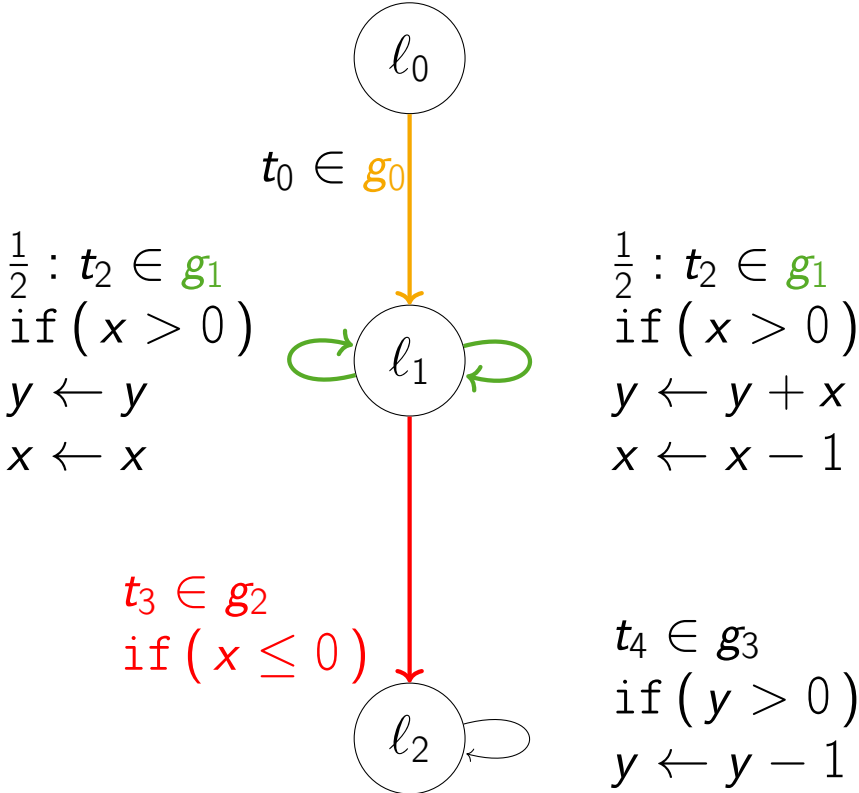
Computation



Computing Expected Size Bounds

Computation

Expected size of v after g_2 :

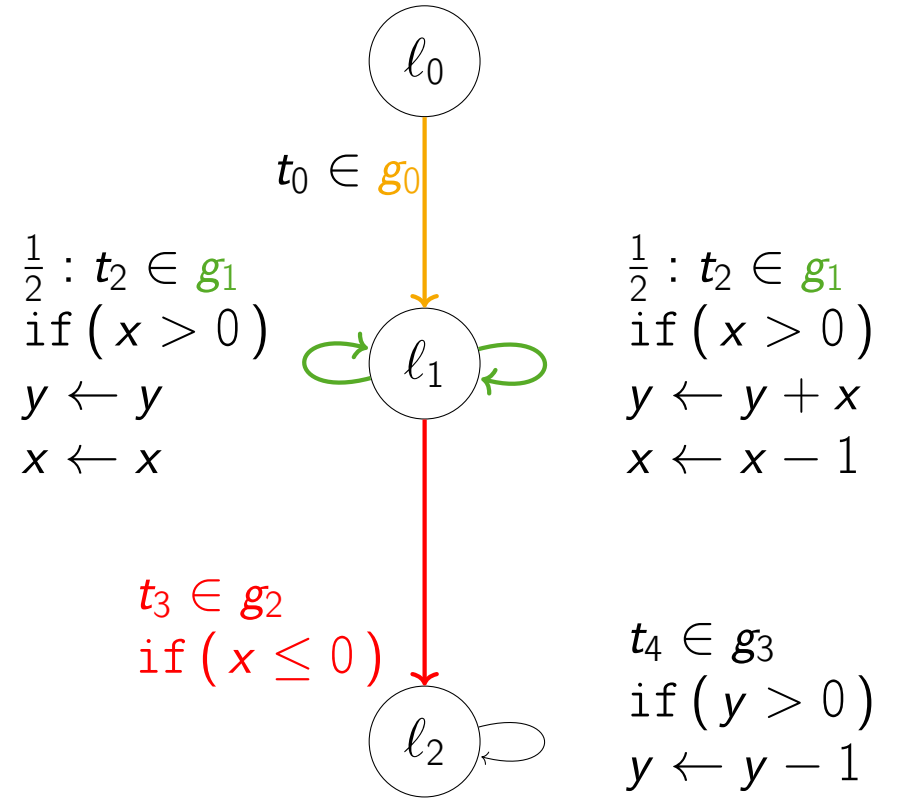


Computing Expected Size Bounds

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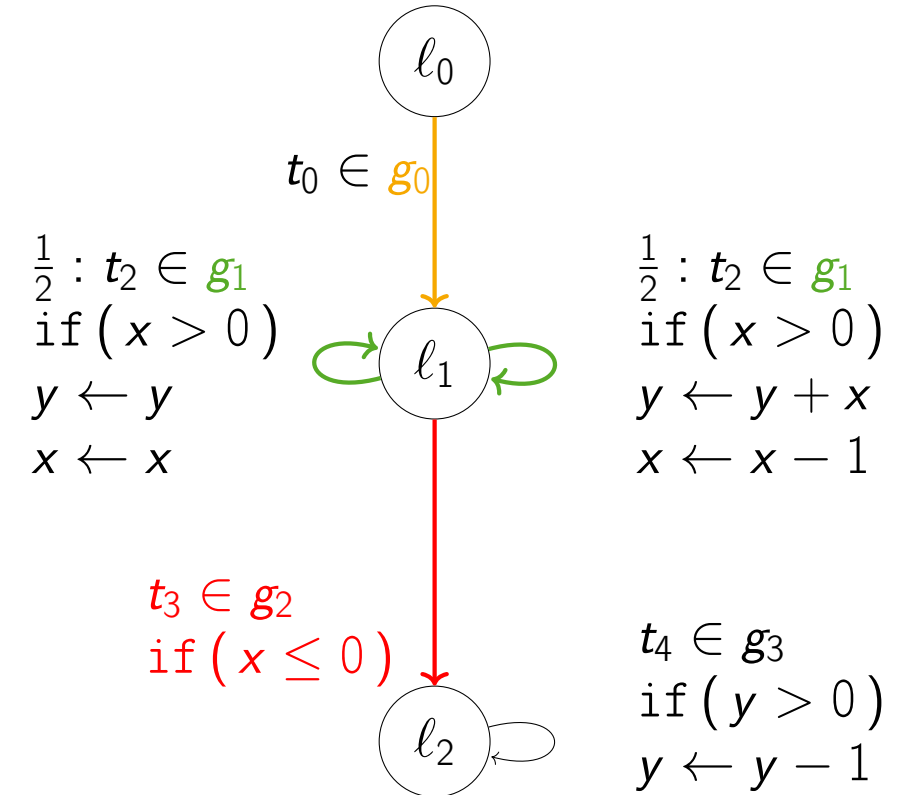
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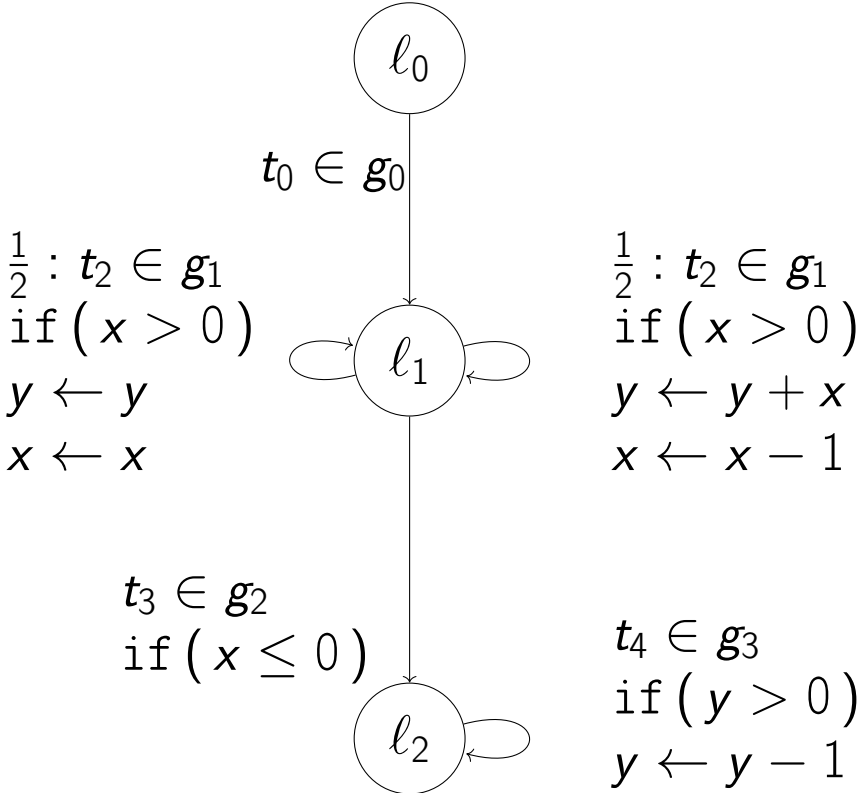
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Computing Expected Size Bounds

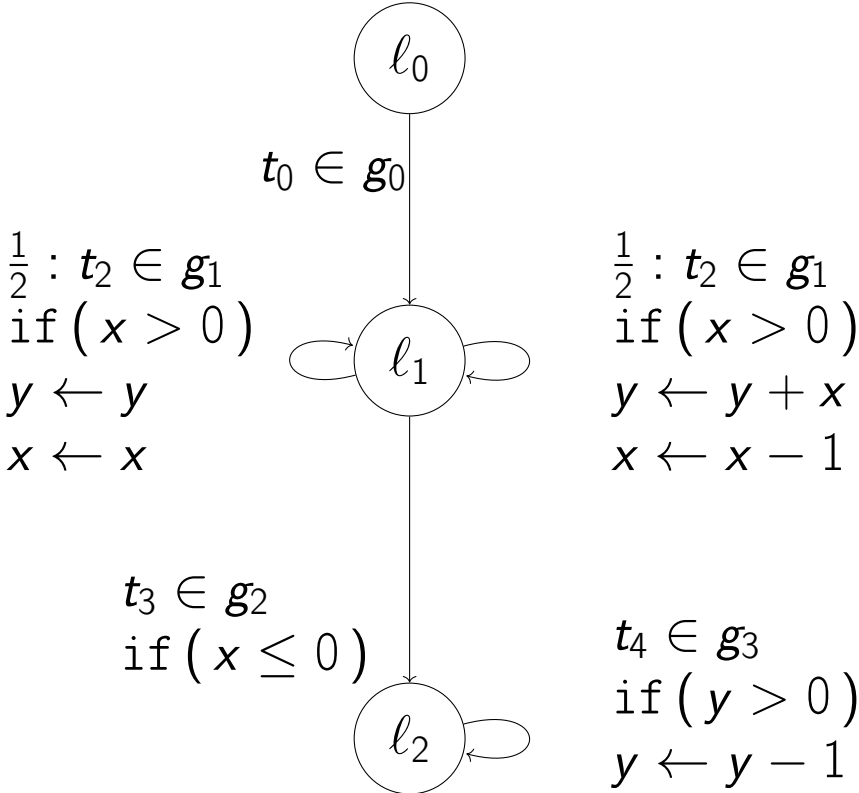
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Computing Expected Size Bounds

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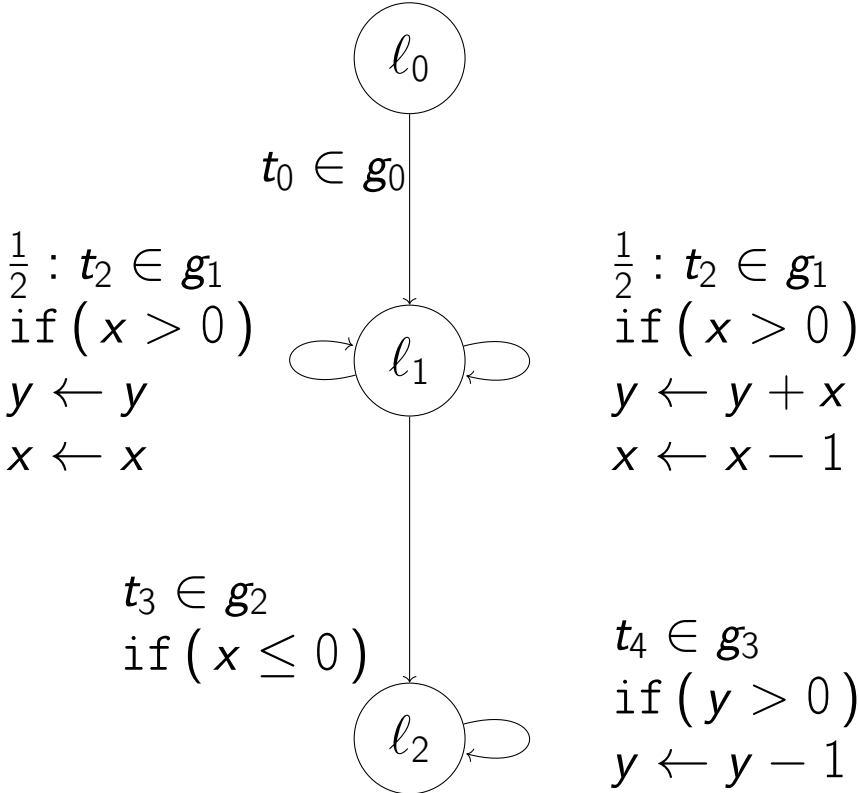
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Computing Expected Size Bounds

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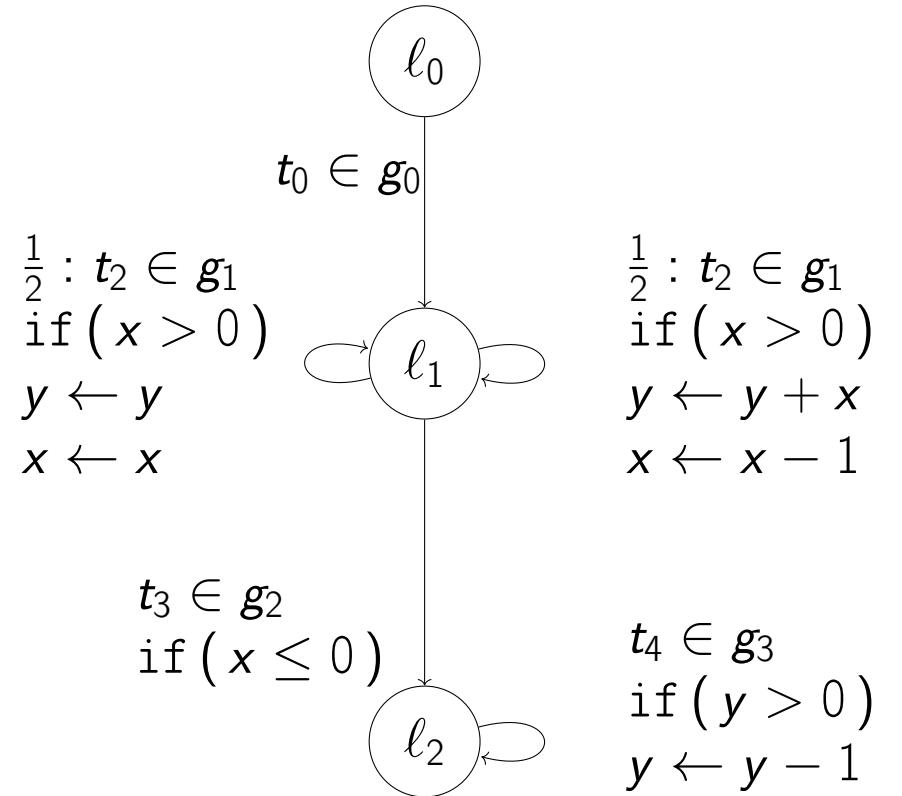
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Computing Expected Size Bounds

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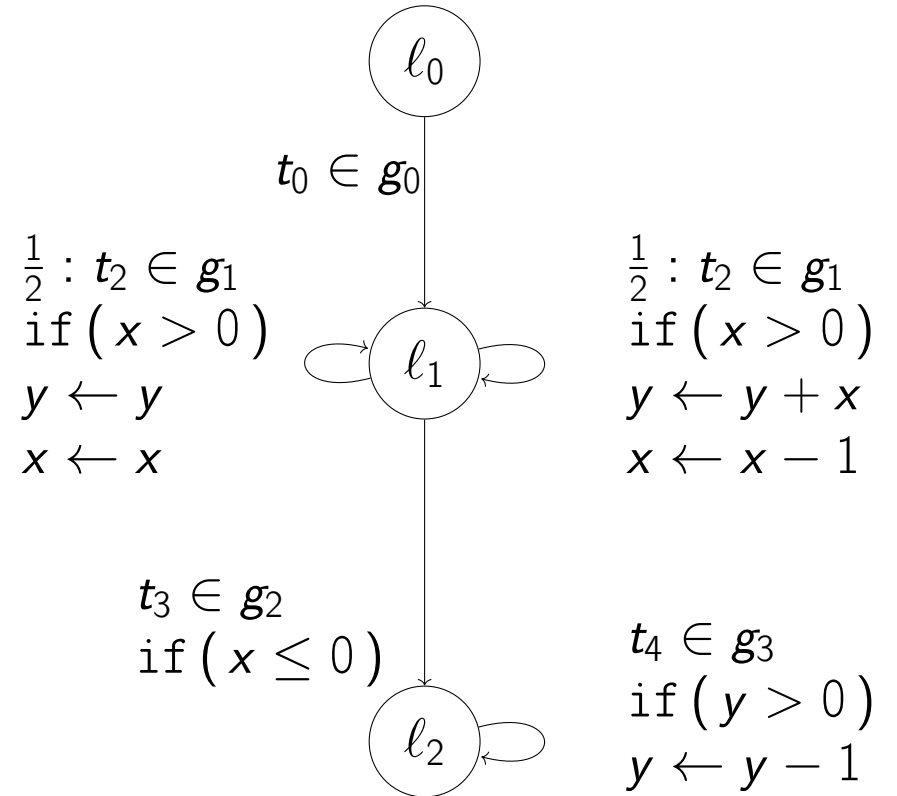
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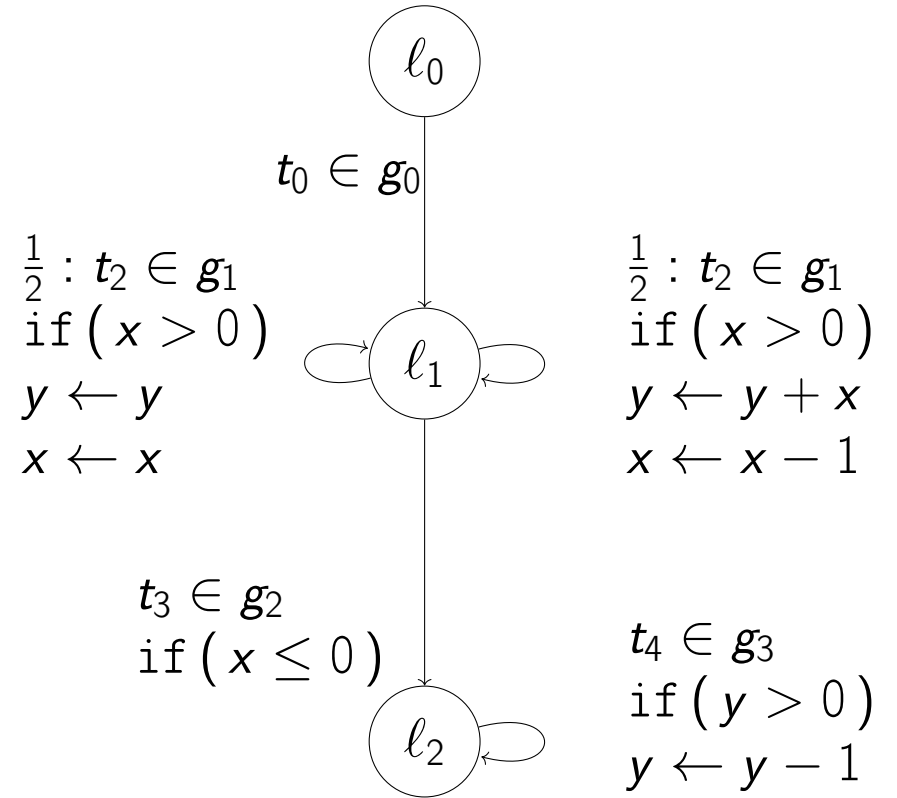
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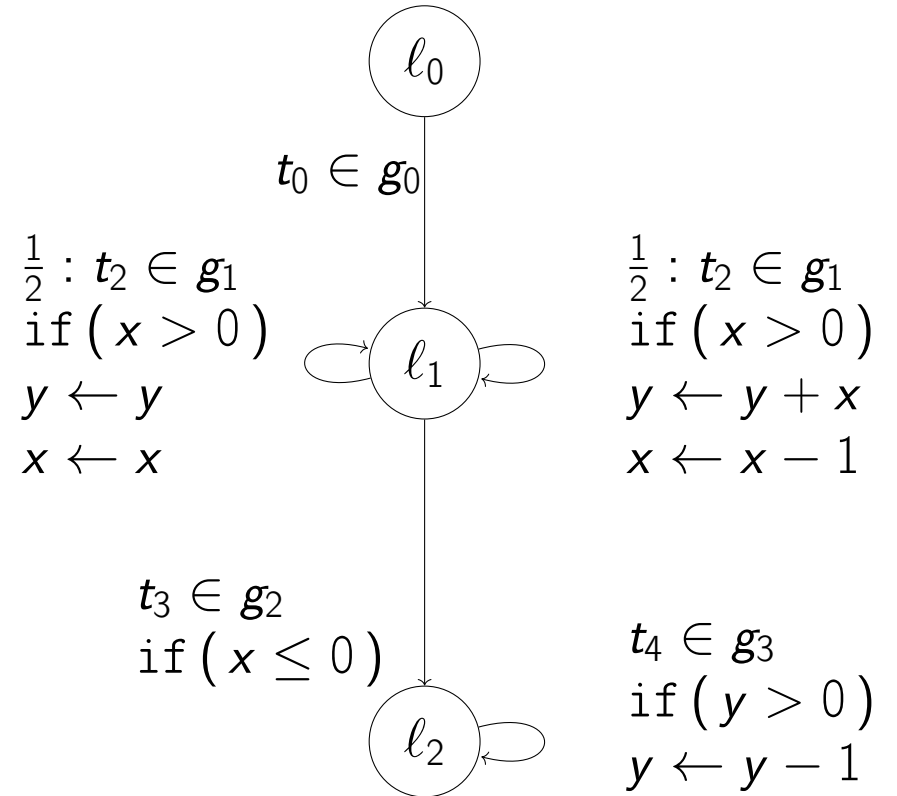
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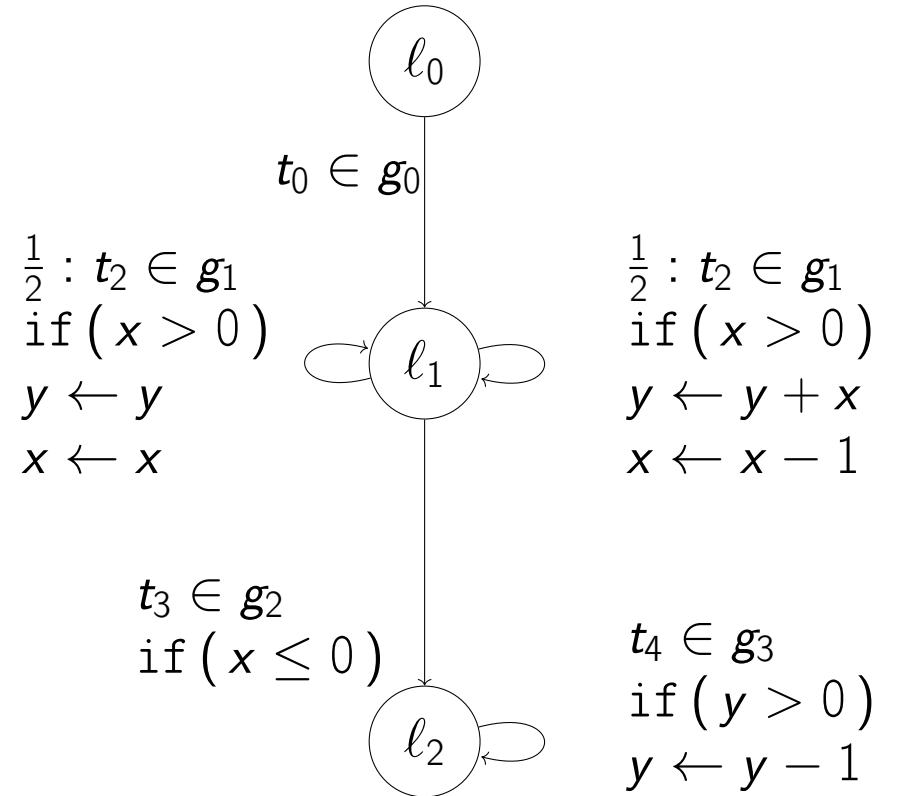
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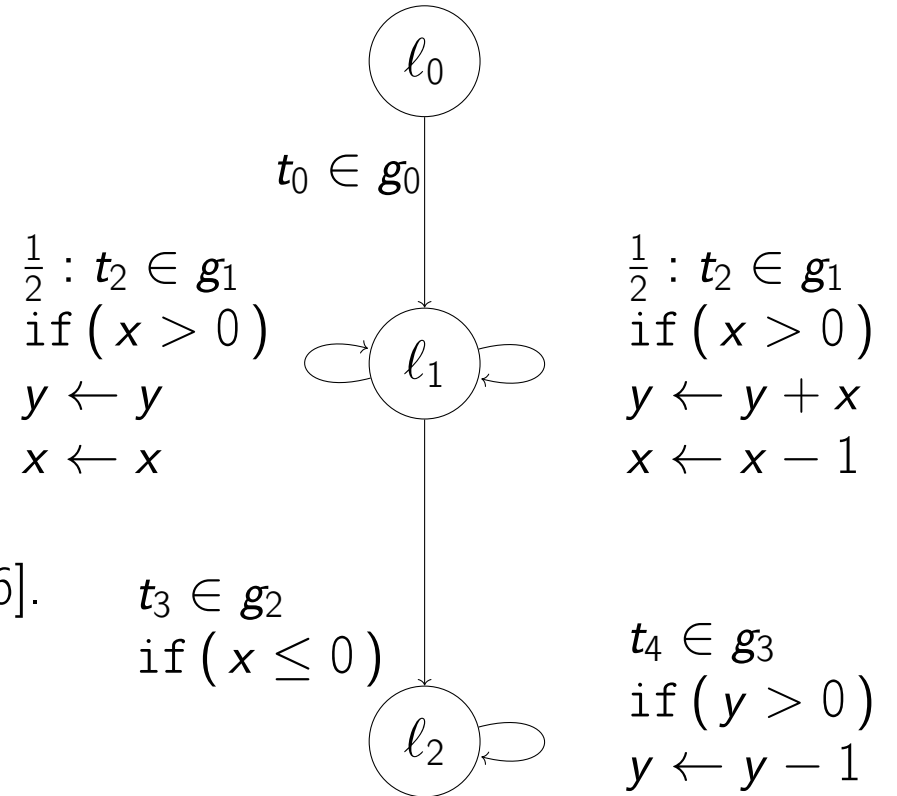
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- Implementation:
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Experiments

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- KoAT especially strong on large examples with many loops but only few randomization.

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- Switch order of analysis (top-down \rightarrow bottom-up).
- Generalize approach to cost-bounds.
- Combination with underlying approach of Absynth resp. eco-imp.

Thank you